## Machine protection

## Specific motor protection

circuits wrs and without current peaks


- Strong overcurrent
- Stalling
capacitors
Protection of resistors, bearings,

- Frequent starting
- Harsh environments
- Overtorque

- Phase failure
- Overtorque
- Mechanical shocks

Classes 5 to 30

## AS-Interface,

 Modbus, CANopen, Advantys STB

- Thermal overload Phase imbalance and phase failure
- Locked rotor

Long starting times - Phase reversal

Earth fault

## Classes 5 to 30

## Modbus, CANopen,

 DeviceNet, Profibus DP
## All contactors

| 0.7...630 A | Unlimited | 0.3...38 A | 0.3...60 A | 0.35...800 A |
| :---: | :---: | :---: | :---: | :---: |
| RM1 XA | LT3 S | LR97D | LT47 | LUTM •0BL |
| Please consult our catalogue "Motor starter solutions". |  |  |  |  |

ase consult our catalogue "Motor Management System TeSys T".

## TeSys protection components

TeSys d 3-pole thermal overload relays

## Presentation



LRD 08••


LRD 365

## X EverLink ${ }^{\circ}$



LRD 33••

TeSys d thermal overload relays are designed to protect a.c. circuits and motors against:
■ overloads,

- phase failure,
- protracted starting times,
- prolonged stalled rotor condition.


## Connection

LRD 01 to LRD 35
LRD 01 to 35 relays are designed for connection by screw clamp terminals. They can be supplied for connection by lugs.

## LRD 313 to LRD 365

LRD 313 to 365 relays are for connection by BTR screw connectors (hexagon socket head).
The screws are tightened by means of a size 4, insulated Allen key.
This type of connection uses the EverLink® system with creep compensation (1) (Schneider Electric patent).
This technique makes it possible to achieve accurate and durable tightening torque.
These relays are also available for connection by lugs.
This type of connection meets the requirements of certain Asian markets and is suitable for applications subject to strong vibration, such as railway transport.

## LRD 3361 to 4369, LRD 2

LRD 3361 to 4369 and LR2 D relays are designed for connection by screw clamp terminals. They can be supplied for connection by lugs.

## Description



LRD 01... 35 and LRD 313...LRD 365


TeSys d 3-pole thermal overload relays are designed to protect a.c. circuits and motors against overloads, phase failure, long starting times and prolonged stalling of the motor.

1 Adjustment dial Ir.
2 Test button.
Operation of the Test button allows:

- checking of control circuit wiring,
- simulation of relay tripping (actuates both the N/O and N/C contacts).

3 Stop button. Actuates the N/C contact; does not affect the N/O contact.
4 Reset button.
5 Trip indicator.
6 Setting locked by sealing the cover.
7 Selector for manual or automatic reset.
LRD 01 to 35 relays are supplied with the selector in the manual position, protected by a cover. Deliberate action is required to move it to the automatic position.

| References: | Dimensions, mounting: | Schemes: |
| :--- | :--- | :--- |
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| Environment |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Conforming to standards |  |  | IEC/EN 60947-4-1, IEC/EN60947-5-1, UL 508, CSAC22.2n ${ }^{\circ} 14$. ATEX directive 94/9/EC (1), (2) |  |  |  |  |  |  |  |
| Product certifications |  |  | UL, CSA. CCC (2). GL, DNV, RINA, BV, LROS (2). ATEX INERIS (1), (2). |  |  |  |  |  |  |  |
| Degree of protection | Conforming to VDE 0106 |  | Protection against direct finger contact IP 2X |  |  |  |  |  |  |  |
| Protective treatment | Conforming to IEC 60068 |  | "TH" |  |  |  |  |  |  |  |
| Ambient air temperature around the device | Storage | ${ }^{\circ} \mathrm{C}$ | -60... 70 |  |  |  |  |  |  |  |
|  | Normal operation, without derating (IEC 60947-4-1) | ${ }^{\circ} \mathrm{C}$ | $-20 \ldots+60$ |  |  |  |  |  |  |  |
|  | Min. and max. operating temperatures (with derating) | ${ }^{\circ} \mathrm{C}$ | $-40 \ldots+70$ |  |  |  |  |  |  |  |
| Operating positions without derating | In relation to normal vertical mounting plane |  | Any position. When mounting on a vertical rail, use a stop. |  |  |  |  |  |  |  |
| Shock resistance | Permissible acceleration conforming to IEC 60068-2-7 |  | $15 \mathrm{gn}-11 \mathrm{~ms}$ |  |  |  |  |  |  |  |
| Vibration resistance | Permissible acceleration conforming to IEC 60068-2-6 |  | 6 gn |  |  |  |  |  |  |  |
| Dielectric strength at 50 Hz | Conforming to IEC 60255-5 | kV | 6 |  |  |  |  |  |  |  |
| Surge withstand | Conforming to IEC 60801-5 | kV | 6 |  |  |  |  |  |  |  |
| Auxiliary contact characteristics |  |  |  |  |  |  |  |  |  |  |
| Conventional thermal current |  | A | 5 |  |  |  |  |  |  |  |
| Maximum sealed consumption of controlled contactor coils (Occasional operating cycles of contact 95-96) | a.c. supply, AC-15 | V | 120 | 240 |  | 380 | 480 | 500 | 600 |  |
|  |  | A | 3 | 1.5 |  | 0.95 | 0.75 | 0.72 | 0.12 |  |
|  | d.c. supply, DC-13 | V | 125 | 250 |  | 440 |  |  |  |  |
|  |  | A | 0.22 | 0.1 | 0.06 |  |  |  |  |  |
| Short-circuit protection | By gG, BS fuses. Max. rating or by GB2 circuit-breaker | A | 5 |  |  |  |  |  |  |  |
| Connection to screw clamp terminals (Min/max c.s.a.) |  |  |  |  |  |  |  |  |  |  |
| Flexible cable without cable end | 1 or 2 conductors | mm ${ }^{2}$ | 1/2.5 |  |  |  |  |  |  |  |
| Flexible cable with cable end | 1 or 2 conductors | mm ${ }^{2}$ | 1/2.5 |  |  |  |  |  |  |  |
| Solid cable without cable end | 1 or 2 conductors | mm ${ }^{2}$ | 1/2.5 |  |  |  |  |  |  |  |
| Tightening torque |  | N.m | 1.7 |  |  |  |  |  |  |  |
| Connection to spring terminals (Min/max c.s.a.) |  |  |  |  |  |  |  |  |  |  |
| Flexible cable without cable end | 1 or 2 conductors | mm ${ }^{2}$ | 1/2.5 |  |  |  |  |  |  |  |
| Flexible cable with cable end | 1 or 2 conductors | mm ${ }^{2}$ | 1/2.5 |  |  |  |  |  |  |  |
| Electrical characteristics of power circuit |  |  |  |  |  |  |  |  |  |  |
| Relay type |  |  | $\begin{array}{\|l\|} \text { LRD } 01 \\ \ldots .16, \\ \text { LR3 D01 } \\ \hline . . D 16 \\ 10 \mathrm{~A} \end{array}$ | LRD 15•॰ | $\begin{aligned} & \text { LRD } 21 \\ & \text {..35, } \\ & \text { LR3 D21 } \\ & \text {...D35 } \end{aligned}$ | $\begin{aligned} & \text { LRD } 313 \\ & \text {... } 365 \end{aligned}$ | $\begin{aligned} & \text { LRD 313L } \\ & \ldots . .365 \mathrm{~L} \end{aligned}$ | $\begin{array}{\|l\|} \text { LRD } 3322 \\ \ldots . .33696 \\ \text { LR3 D3322 } \\ \hline . . \text { D33696 } \\ \hline \end{array}$ | LR2 D35•e | $\begin{array}{\|l\|l\|} \hline \text { LRD } \\ 4365 \\ \ldots . .4369 \end{array}$ |
| Tripping class | Conforming to UL 508, IEC 60947-4-1 |  |  | 20 | 10 A | 10 A | 20 | 10 A | 20 | 10 A |
| Rated insulation voltage (Ui) | Conforming to IEC 60947-4-1 | V | 690 |  | 690 | 690 | 690 | 1000 |  | 1000 |
|  | Conforming to UL, CSA | V | 600 |  | 600 | 600 | 600 | 600 |  | $\begin{aligned} & \hline \text { 600ex. } \\ & \text { LRD4369 } \end{aligned}$ |
| Rated impulse withstand voltage (Uimp) |  | kV | 6 |  | 6 | 6 | 6 | 6 |  | 6 |
| Frequency limits | Of the operational current | Hz | 0... 400 |  | 0... 400 | 0... 400 | 0... 400 | 0... 400 |  | 0... 400 |
| $\frac{\text { Setting range }}{\text { Connection to screw clamp terminals (Min/max c.s.a.) }}$ |  | A | 0.1... 13 |  | 12... 38 | 9... 65 | 9... 65 | 17... 104 |  | 80... 140 |
|  |  |  | 1.5/10 |  | 1.5/10 |  |  |  |  |  |
| Flexible cable without cable end | 1 conductor | $\mathrm{mm}^{2}$ |  |  | 1/35 | 1/35 | 4/35 |  | 4/50 |
| Flexible cable with cable end | 1 conductor | mm ${ }^{2}$ | 1/4 |  |  | 1/6ex. LRD21:1/4 | 1/35 | 1/35 | 4/35 |  | 4/35 |
| Solid cable without cable end | 1 conductor | $\mathrm{mm}^{2}$ | 1/6 |  | 1.5/10 ex. LRD21:16 | 1/35 | 1/35 | 4/35 |  | 4/50 |
| Tightening torque |  | N.m | 1.7 | 1.85 | 2.5 | $\begin{aligned} & 1 / 25: 5 \\ & 35: 8 \end{aligned}$ | $\begin{aligned} & 1 / 25: 5 \\ & 35: 8 \end{aligned}$ | 9 | 9 | 9 |
| Connection to spring terminals (Min/max c.s.a.) |  |  |  |  |  |  |  |  |  |  |
| Flexible cable without cable end | 1 conductor | mm ${ }^{2}$ | 1.5/4 | - | 1.5/4 | - | - | - | - | - |
| Flexible cable with cable end | 1 conductor | mm ${ }^{2}$ | 1.5/4 | - | 1.5/4 | - | - | - | - | - |

(1) For LRD01 to LRD365 relays.
(2) Pending for relays LRD313 to LRD365.

TeSys protection components
TeSys d 3-pole thermal overload relays

## Connection by bars or lugs



[^0]| References: | Dimensions, mounting: | Schemes: |
| :--- | :--- | :--- |
| page 204 | page 210 | page 213 |

TeSys protection components TeSys d 3-pole thermal overload relays

| Operating characteristics |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Relay type |  |  | $\begin{array}{\|l} \text { LRD } 01 \\ \ldots 16, \\ \text { LR3 D01 } \\ \text {...D16 } \end{array}$ | LRD 150. | $\begin{array}{\|l} \text { LRD 21 } \\ \text { ‥35, } \\ \text { LR3 D21 } \\ \text {...D35 } \end{array}$ | $\begin{aligned} & \text { LRD } 313 \\ & \ldots . .365 \end{aligned}$ |  | LRD 3322 <br> $\ldots 33696$ <br> LR3 <br> D3322... <br> D33696 | LR2 D35•• | $\begin{aligned} & \text { LRD } \\ & 4365 \\ & \ldots . .4369 \end{aligned}$ |
| Temperature compensation |  | ${ }^{\circ} \mathrm{C}$ | $-20 \ldots+60$ |  | $\begin{aligned} & -30 \ldots+ \\ & 60 \end{aligned}$ | $-20 \ldots+60$ |  | $-30 \ldots+60$ |  | $\begin{aligned} & -20 \ldots+ \\ & 60 \end{aligned}$ |
| Tripping threshold | Conforming to EC 60947-4-1 | A | $1.14 \pm 0.0$ | 6 Ir |  |  |  |  |  |  |
| Sensitivity to phase failure | Conforming to IEC 60947-4-1 |  | Tripping current I $30 \%$ of Ir on one phase, the others at Ir. |  |  |  |  |  |  |  |

## Tripping curves

Average operating time related to multiples of the setting current
LRD 33••, LR2 D


## LRD 3




1 Balanced operation, 3-phase, from cold state.
2 2-phase operation, from cold state.
3 Balanced operation, 3-phase, after a long period at the set current (hot state).

| References: | Dimensions, mounting: | Schemes: |
| :--- | :--- | :--- |
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Description, characteristics

## TeSys protection components

3-pole electronic thermal overload relays, TeSys LR9 D

Description


LR9 D5367...D5569


LR9 D67 and D69

LR9 D electronic thermal overload relays are designed for use with contactors LC1 D115 and D150.

In addition to the protection provided by TeSys d thermal overload relays (see page 24516/2), they offer the following special features:

- protection against phase imbalance,
- choice of starting class,
- protection of unbalanced circuits,
- protection of single-phase circuits,
- alarm function to avoid tripping by load shedding.

1 Adjustment dial Ir.
2 Test button.
3 Stop button.
4 Reset button.
5 Trip indicator.
6 Setting locked by sealing the cover.
7 Class 10/class 20 selector switch.
8 Switch for
balanced load 入 /unbalanced load 凤

| Environment |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Conforming to standards |  |  | IEC 60947-4-1, 255-8, 255-17, VDE 0660 and EN 60947-4-1 |  |  |  |  |  |
| Product certifications |  |  | UL 508, CSA 22-2 |  |  |  |  |  |
| Degree of protection | Conforming to IEC 60529 and VDE 0106 |  | IP 20 on front panel with protective covers LA9 D11570^ or D11560 |  |  |  |  |  |
| Protective treatment | Standard version |  | "TH" |  |  |  |  |  |
| Ambient air temperature around the device (Conforming to IEC 60255-8) | Storage | ${ }^{\circ} \mathrm{C}$ | $-40 \ldots+85$ |  |  |  |  |  |
|  | Normal operation | ${ }^{\circ} \mathrm{C}$ | -20... 55 (1) |  |  |  |  |  |
| Maximum operating altitude | Without derating | m | 2000 |  |  |  |  |  |
| Operating positions without derating | In relation to normal vertical mounting plane |  | Any position |  |  |  |  |  |
| Shock resistance | Permissible acceleration conforming to IEC 60068-2-7 |  | $13 \mathrm{gn}-11 \mathrm{~ms}$ |  |  |  |  |  |
| Vibration resistance | Permissible acceleration conforming to IEC 60068-2-6 |  | $2 \mathrm{gn}-5 \ldots 300 \mathrm{~Hz}$ |  |  |  |  |  |
| Dielectric strength at 50 Hz | Conforming to IEC 60255-5 | kV | 6 |  |  |  |  |  |
| Surge withstand | Conforming to IEC 61000-4-5 | kV | 6 |  |  |  |  |  |
| Resistance to electrostatic discharge | Conforming to IEC 61000-4-2 | kV | 8 |  |  |  |  |  |
| Immunity to radiated radio-frequency disturbance | Conforming to IEC 61000-4-3 and NF C 46-022 | V/m | 10 |  |  |  |  |  |
| Immunity to fast transient currents | Conforming to IEC 61000-4-4 | kV | 2 |  |  |  |  |  |
| Electromagnetic compatibility Draft EN 50081-1 and 2, EN 50082-2 |  |  | Meet requirements |  |  |  |  |  |
| Electrical characteristics of auxiliary contacts |  |  |  |  |  |  |  |  |
| Conventional thermal current |  | A | 5 |  |  |  |  |  |
| Maximum sealed current consumption of controlled contactor coils (Occasional operating cycles of contact 95-96) | a.c. supply | V | 24 | 48 | 110 | 220 | 380 | 600 |
|  |  | VA | 100 | 200 | 400 | 600 | 600 | 600 |
|  | d.c. supply | V | 24 | 48 | 110 | 220 | 440 | - |
|  |  | W | 100 | 100 | 50 | 45 | 25 | - |
| Short-circuit protection | By gG or BS fuses or by circuit-breaker GB2 | A | 5 |  |  |  |  |  |
| Connection <br> Flexible cable without cable end | 1 or 2 conductors | $\mathrm{mm}^{2}$ | Minimum c.s.a.: 1 <br> Maximum c.s.a.: 2.5 |  |  |  |  |  |
|  | Tightening torque | Nm | 1.2 |  |  |  |  |  |

(1) For operating temperatures up to $70^{\circ} \mathrm{C}$, please consult your Regional Sales Office.

| References: | Dimensions, mounting: | Schemes: |
| :--- | :--- | :--- |
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Characteristics (continued)
TeSys protection components 3-pole electronic thermal overload relays, TeSys LR9 D

| Relay type |  |  | LR9 D |
| :---: | :---: | :---: | :---: |
| Electrical characteristics of power circuit |  |  |  |
| Tripping class | Conforming to UL 508, IEC 60947-4-1 | A | 10 or 20 |
| Rated insulation voltage (Ui) | Conforming to IEC 60947-4-1 | V | 1000 |
|  | Conforming to UL, CSA | V | 600 |
| Rated impulse withstand voltage (Uimp) |  | Hz | 8 |
| Frequency limits | Of the operating current | Hz | 50... 60 (1) |
| Setting range | Depending on model | A | 60... 150 |
| Power circuit connections | Width of terminal lug | mm | 20 |
|  | Clamping screw |  | M8 |
|  | Tightening torque | N.m | 18 |
| Operating characteristics |  |  |  |
| Temperature compensation |  | ${ }^{\circ} \mathrm{C}$ | $-20 . . .+70$ |
| Tripping thresholds | Conforming to IEC 60947-4-1 <br> Alarm | A | $1.05 \pm 0.06 \mathrm{ln}$ |
|  | De-energisation | A | $1.12 \pm 0.06 \mathrm{ln}$ |
| Sensitivity to phase failure | Conforming to IEC 60947-4-1 |  | Tripping in $4 \mathrm{~s} \pm 20 \%$ in the event of phase failure |
| Alarm circuit characteristics |  |  |  |
| Rated supply voltage | d.c. supply | V | 24 |
| Supply voltage limits |  | V | 17... 32 |
| Current consumption | No-load | mA | $\leqslant 5$ |
| Switching capacity |  | mA | 0... 150 |
| Protection | Short-circuit and overload |  | Self protected |
| Voltage drop | Closed state | V | $\leqslant 2.5$ |
| Connection | Flexible cable without cable end | $\mathrm{mm}^{2}$ | 0.5...1.5 |
| Tightening torque |  | N.m | 0.45 |
|  |  | (1) For speed | plications involving the use of these overload relay位位, please consult your Regional Sales Office. |

## LR9 D tripping curves



1 Cold state curve


LRD 08••


LRD 21••


LRD 3••


LRD 3••6

Differential thermal overload relays
for use with fuses and magnetic circuit-breakers GV2 L and GV3 L

- Compensated relays with manual or automatic reset,
- with relay trip indicator,
- for a.c. or d.c.

| Relay setting range (A) | Fuses to be used with selected relay |  |  | For use with contactor LC1 | Reference | Weight kg |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | aM (A) | gG (A) | BS88 (A) |  |  |  |
| Class 10 A (1) for connection by screw clamp terminals or connectors |  |  |  |  |  |  |
| 0.10...0.16 | 0.25 | 2 | - | D09...D38 | LRD 01 | 0.124 |
| 0.16...0.25 | 0.5 | 2 | - | D09...D38 | LRD 02 | 0.124 |
| 0.25...0.40 | 1 | 2 | - | D09...D38 | LRD 03 | 0.124 |
| 0.40...0.63 | 1 | 2 | - | D09...D38 | LRD 04 | 0.124 |
| 0.63... 1 | 2 | 4 | - | D09...D38 | LRD 05 | 0.124 |
| 1...1.6 | 2 | 4 | 6 | D09...D38 | LRD 06 | 0.124 |
| 1.6...2.5 | 4 | 6 | 10 | D09...D38 | LRD 07 | 0.124 |
| 2.5... 4 | 6 | 10 | 16 | D09...D38 | LRD 08 | 0.124 |
| 4...6 | 8 | 16 | 16 | D09...D38 | LRD 10 | 0.124 |
| 5.5... 8 | 12 | 20 | 20 | D09...D38 | LRD 12 | 0.124 |
| 7... 10 | 12 | 20 | 20 | D09...D38 | LRD 14 | 0.124 |
| 9...13 | 16 | 25 | 25 | D12...D38 | LRD 16 | 0.124 |
| 12... 18 | 20 | 35 | 32 | D18...D38 | LRD 21 | 0.124 |
| 16... 24 | 25 | 50 | 50 | D25...D38 | LRD 22 | 0.124 |
| 23... 32 | 40 | 63 | 63 | D25...D38 | LRD 32 | 0.124 |
| 30... 38 | 40 | 80 | 80 | D32 and D38 | LRD 35 | 0.124 |

Class 10 A (1) for connection by EverLink ${ }^{\circledR}$, BTR screw connectors (3)

| $9 \ldots 13$ | 16 | 25 | 25 | D40A...D65A | LRD 313 | 0.375 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $12 \ldots 18$ | 20 | 32 | 35 | D40A...D65A | LRD 318 | 0.375 |
| $16 \ldots 25$ | 25 | 50 | 50 | D40A...D65A | LRD 325 | 0.375 |
| $23 \ldots 32$ | 40 | 63 | 63 | D40A...D65A | LRD 332 | 0.375 |
| $25 \ldots 40$ | 40 | 80 | 80 | D40A...D65A | LRD 340 | 0.375 |
| $37 \ldots 50$ | 63 | 100 | 100 | D40A...D65A | LRD 350 | 0.375 |
| $48 \ldots 65$ | 63 | 100 | 100 | D50A...D65A | LRD 365 | 0.375 |

Class 10 A (1) for connection by screw clamp terminals or connectors

| $55 \ldots 70$ | 80 | 125 | 125 | D50 ...D95 | LRD 3361 | 0.510 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $63 \ldots 80$ | 80 | 125 | 125 | D65 ...D95 | LRD 3363 | 0.510 |
| $80 \ldots 104$ | 100 | 160 | 160 | D80 and D95 | LRD 3365 | 0.510 |
| $80 \ldots 104$ | 125 | 200 | 160 | D115 and D150 | LRD 4365 | 0.900 |
| $95 \ldots 120$ | 125 | 200 | 200 | D115 and D150 | LRD 4367 | 0.900 |
| $110 \ldots 140$ | 160 | 250 | 200 | D150 | LRD 4369 | 0.900 |
| $80 \ldots 104$ | 100 | 160 | 160 | $(2)$ | LRD 33656 | 1.000 |
| $95 \ldots 120$ | 125 | 200 | 200 | $(2)$ | LRD 33676 | 1.000 |
| $110 \ldots 140$ | 160 | 250 | 200 | $(2)$ | LRD 33696 | 1.000 |

Class 10 A (1) for connection by lugs
Select the appropriate overload relay with screw clamp terminals or connectors from the table above and add one of the following suffixes:

- figure 6 for relays LRD 01 to LRD 35 and relays LRD 313 to LRD 365.
- A66 for relays LRD 3361 to LRD 3365.

Relays LRD 43•e are suitable, as standard, for use with lug-clamps.

## Thermal overload relays for use with unbalanced loads

Class 10 A (1) for connection by screw clamp terminals or lugs
In the references selected above, change the prefix LRD (except LRD 4•eゃ) to LR3 D.
Example: LRD 01 becomes LR3 D01.
Example with screw clamp connections: LRD 340 becomes LR3D 340.
Example with lugs: LRD 3406 becomes LR3 D 3406.
(1) Standard IEC 60947-4-1 specifies a tripping time for 7.2 times the setting current $I_{R}$ :
class 10 A : between 2 and 10 seconds
(2) Independent mounting of the contactor.
(3) BTR screws: hexagon socket head. In accordance with local electrical wiring regulations, a size 4 insulated Allen key must be used (reference LAD ALLEN4, see page 173).


| Differential thermal overload relays <br> for use with fuses and magnetic circuit-breakers GV2 L and GV3 L (continued) |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Compensated relays with manual or automatic reset, with relay trip indicator, for a.c. or d.c. |  |  |  |  |  |  |
| Relay setting range (A) | Fuses to be used with selected relay |  |  | For use with contactor LC1 | Reference | Weight kg |
|  | aM (A) | gG (A) | BS88 (A) |  |  |  |
| Class 10 A (1) for connection by spring terminals (only for direct mounting beneath the contactor) |  |  |  |  |  |  |
| 0.10...0.16 | 0.25 | 2 | - | D09...D38 | LRD 013 | 0.140 |
| 0.16...0.25 | 0.5 | 2 | - | D09...D38 | LRD 023 | 0.140 |
| 0.25...0.40 | 1 | 2 | - | D09...D38 | LRD 033 | 0.140 |
| 0.40...0.63 | 1 | 2 | - | D09...D38 | LRD 043 | 0.140 |
| 0.63... 1 | 2 | 4 | - | D09...D38 | LRD 053 | 0.140 |
| 1...1.6 | 2 | 4 | 6 | D09...D38 | LRD 063 | 0.140 |
| 1.6...2.5 | 4 | 6 | 10 | D09...D38 | LRD 073 | 0.140 |
| 2.5... 4 | 6 | 10 | 16 | D09...D38 | LRD 083 | 0.140 |
| 4...6 | 8 | 16 | 16 | D09...D38 | LRD 103 | 0.140 |
| 5.5... 8 | 12 | 20 | 20 | D09...D38 | LRD 123 | 0.140 |
| 7... 10 | 12 | 20 | 20 | D09...D38 | LRD 143 | 0.140 |
| 9...13 | 16 | 25 | 25 | D12...D38 | LRD 163 | 0.140 |
| 12... 18 | 20 | 35 | 32 | D18...D38 | LRD 213 | 0.140 |
| 16... 24 | 25 | 50 | 50 | D25...D38 | LRD 223 | 0.140 |

Class 10 A for power connection by EverLink ${ }^{\circledR}$, BTR screw connectors (2) and control by spring terminals

| $9 \ldots 13$ | 16 | 25 | 25 | D40A...D65A | LRD 3133 | 0.375 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $12 \ldots 18$ | 20 | 32 | 35 | D40A..D65A | LRD 3183 | 0.375 |
| $16 \ldots 25$ | 25 | 50 | 50 | D40A...D65A | LRD 3253 | 0.375 |
| $23 \ldots 32$ | 40 | 63 | 63 | D40A...D65A | LRD 3323 | 0.375 |
| $25 \ldots 40$ | 40 | 80 | 80 | D50A...D65A | LRD 3403 | 0.375 |
| $37 \ldots 50$ | 63 | 100 | 100 | D40A...D65A | LRD 3503 | 0.375 |
| $48 \ldots 65$ | 63 | 100 | 100 | D50A...D65A | LRD 3653 | 0.375 |

## Thermal overload relays for use with unbalanced loads

Class 10 A (1) for power connection by BTR screw connectors (2) and control by spring terminals In the references selected above, replace LRD 3 with LR3 D3.
Example: LRD 3653 becomes LR3D 3653.

## Thermal overload relays for use on 1000 V supplies

Class 10 A (1) for connection by screw clamp terminals
For relays LRD 06 to LRD 35 only, for an operating voltage of 1000 V , and only for independent mounting, the reference becomes LRD 33e๑A66.
Example: LRD 12 becomes LRD 3312A66.
Order an LA7 D3064 terminal block separately, see page 209.

[^1]

LRD 15••


LRD 3 $\bullet \circ$ L


LR2 D35eゃL

Differential thermal overload relays
for use with fuses and magnetic circuit-breakers GV2 L and GV3 L (continued)

- Compensated relays with manual or automatic reset,
- with relay trip indicator,
- for a.c. or d.c.

| Relay setting range (A) | Fuses to be used with selected relay |  |  | For use with contactor LC1 | Reference | Weight kg |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | aM (A) | gG (A) | BS88 (A) |  |  |  |
| Class 20 (1) for connection by screw clamp terminals |  |  |  |  |  |  |
| 2.5... 4 | 6 | 10 | 16 | D09...D32 | LRD 1508 | 0.190 |
| 4... 6 | 8 | 16 | 16 | D09...D32 | LRD 1510 | 0.190 |
| 5.5... 8 | 12 | 20 | 20 | D09...D32 | LRD 1512 | 0.190 |
| 7... 10 | 16 | 20 | 25 | D09...D32 | LRD 1514 | 0.190 |
| 9... 13 | 16 | 25 | 25 | D12...D32 | LRD 1516 | 0.190 |
| 12... 18 | 25 | 35 | 40 | D18...D32 | LRD 1521 | 0.190 |
| 17... 25 | 32 | 50 | 50 | D25 and D32 | LRD 1522 | 0.190 |
| 23... 28 | 40 | 63 | 63 | D25 and D32 | LRD 1530 | 0.190 |
| 25... 32 | 40 | 63 | 63 | D25 and D32 | LRD 1532 | 0.190 |
| 9... 13 | 20 | 32 | 35 | D40A...D65A | LRD 313L | 0.375 |
| 12... 18 | 25 | 40 | 40 | D40A...D65A | LRD 318L | 0.375 |
| 16... 25 | 32 | 50 | 50 | D40A...D65A | LRD 325L | 0.375 |
| 23... 32 | 40 | 63 | 63 | D40A...D65A | LRD 332L | 0.375 |
| 25... 40 | 50 | 80 | 80 | D40A...D65A | LRD 340L | 0.375 |
| 37... 50 | 63 | 100 | 100 | D40A...D65A | LRD 350L | 0.375 |
| 48... 65 | 80 | 125 | 125 | D40A...D65A | LRD 365L | 0.375 |
| 55... 70 | 100 | 125 | 125 | D65...D95 | LR2 D3561 | 0.535 |
| 63... 80 | 100 | 160 | 125 | D80 and D95 | LR2 D3563 | 0.535 |

[^2]
## Differential thermal overload relays

for use with fuses and magnetic circuit-breakers GV2 L and GV3 L (continued)
■ Compensated relays, with relay trip indicator,

- for a.c.,
- for direct mounting or independent mounting (1).

| Relay setting range (A) | Fuses to be used with selected relay |  | For mounting beneath contactor LC1 | Reference | Weight kg |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | aM (A) | gG (A) |  |  |  |
| Class 10 or 10A (2) for connection using bars or connectors |  |  |  |  |  |
| 60... 100 | 100 | 160 | D115 and D150 | LR9 D5367 | 0.885 |
| 90... 150 | 160 | 250 | D115 and D150 | LR9 D5369 | 0.885 |
| Class 20 (2) for connection using bars or connectors |  |  |  |  |  |
| 60... 100 | 125 | 160 | D115 and D150 | LR9 D5567 | 0.885 |
| 90... 150 | 200 | 250 | D115 and D150 | LR9 D5569 | 0.885 |

## Electronic thermal overload relays for use with balanced or unbalanced loads

■ Compensated relays,

- with separate outputs for alarm and tripping.

| Relay setting range (A) | Fuses aM (A) | $\begin{aligned} & \text { used w } \\ & \text { gG (A) } \end{aligned}$ | For mounting beneath contactor LC1 | Reference | Weight kg |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Class 10 or $\mathbf{2 0}$ (2) selectable, for connection using bars or connectors |  |  |  |  |  |
| 60... 100 | 100 | 160 | D115 and D150 | LR9 D67 | 0,900 |
| 90... 150 | 160 | 250 | D115 and D150 | LR9 D69 | 0,900 |

(1) Power terminals can be protected against direct finger contact by the addition of covers and/or insulated terminal blocks, to be ordered separately (see page 172).
(2) Standard IEC 60947-4-1 specifies a tripping time for 7.2 times the setting current $I_{R}$ : class 10: between 4 and 10 seconds,
class 10 A: between 2 and 10 seconds,
class 20 A: between 6 and 20 seconds

Other versions $\quad$ Thermal overload relays for resistive circuits in category AC-1.
Please consult your Regional Sales Office.



LAD 7C•


LAD 7B106


LAD 96570
LAD 96575

| Separate components for relays |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Description | For use with | Sold in lots of | Unit reference | Weight kg |
| Pre－wiring kit allowing direct connection of the N／C contact of relay LRD 01 ．．． 35 or LR3 D01．．．D35 to the contactor | LC1 D09．．．D18 | 10 | LAD 7C1（1） | 0.002 |
|  | LC1 D25．．．D38 | 10 | LAD 7C2（1） | 0.003 |
| ```Terminal block (2) for clip-on mounting on 35 mm rail (AM1 DP200) or screw fixing; for fixing centres, see page 210 to 212``` | LRD 01．．． 35 and LR3 D01．．．D35 | 1 | LAD 7B106 | 0.100 |
|  | LRD 1508．．． 32 | 1 | LAD 7B105 | 0.100 |
|  | LRD 33••๑，LR3 D33•⿰๑，LR2 D35•• | 1 | LA7 D3064（3） | 0.370 |
| EverLink ${ }^{\circledR}$ terminal block for independent mounting | LRD 3・ャ，LRD 3 ${ }^{\circ} \mathrm{L}$ and LR3 D3 ${ }^{\text {e }}$ | 1 | LAD 96560 | 0.087 |
| Size 4 Allen key，insulated， 1000 V | LRD 3•๑，LRD 3 ${ }^{\text {eL }}$ and LR3 D3 $\bullet \bullet$ | 5 | LAD ALLEN4 | 0.026 |
| Terminal block adapter for mounting a relay beneath an LC1 D115 or D150 contactor | LRD 3・ャ，LR3 D3・セセ，LRD 35•๑ | 1 | LA7 D3058（3） | 0.080 |
| Mounting plates（4） for screw fixing on 110 mm centres | $\begin{aligned} & \text { LRD 01...35, LR3 D01...D35, LRD } \\ & 1508 \ldots 32 \end{aligned}$ | 10 | DX1 AP25 | 0.065 |
|  | LRD 3•⿰๑，LR3 D3•⿰๑，LR2 D35•• | 1 | LA7 D902 | 0.130 |
| Marker holders， snap－in $8 \times 18 \mathrm{~mm}$ | LRD 3 $\bullet \bullet$ | 100 | LAD 90 | 0.001 |
|  | All relays except LRD 01．．．35， LR3 D01．．．D35，LRD 3•e，LRD 3・ゃL and LR3 D3 $\bullet \bullet$ | 100 | LA7 D903 | 0.001 |
| Bag of 400 blank legends （self－adhesive， $7 \times 16 \mathrm{~mm}$ ） | All relays | 1 | LA9 D91 | 0.001 |
| Stop button locking device | All relays except LRD 01．．．35， LR3 D01．．．D35，LR9 D and LRD 313．．．LRD 365 | 10 | LA7 D901 | 0.005 |
| Remote Stop or electrical reset device（5） | LRD 01．．．35，LR3 D01．．．D35 and LRD 313．．．LRD 365 | 1 | LAD 703•（6）（7） | 0.090 |
| Remote tripping or electrical reset device（5） | All relays except LRD 01．．．35， LR3 D01．．．D35，LRD 3・ゃ，LRD 3・ゃL and LR3 D3 $\bullet \bullet$ | 1 | LA7 D03•（6） | 0.090 |
| Block of insulated terminals | LR9 D | 2 | LA9 F103 | 0.560 |
| IP 20 cover for lug type terminals for independent mounting | LRD 3136．．． 3656 | 1 | LAD 96570 | 0.021 |
| IP 20 cover for lug type terminals for mounting with contactor LC1 D40A6．．．D65A6 | LRD 3136．．． 3656 | 1 | LAD 96575 | 0.010 |
| Terminal block for lug type terminals for independent mounting | LRD 3136．．． 3656 | 1 | LAD 96566 | 0.010 |


| Remote control |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| ＂Reset＂function | For use with |  |  |  |
| Description |  |  |  |  |

The terminal protection shroud must be removed and the following 3 products must be ordered separately：

| Adapter for door mounting | LRD 33••，LR2 D and LRD 15 $\bullet \bullet$ | 1 | LA7 D1020 | 0.005 |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Operating heads <br> for spring return pushbutton | Stop | All relays | 1 | XB5 AL84101 | 0.027 |
|  | Reset | All relays | 1 | XB5 AA86102 | 0.027 |

（1）These pre－wiring kits cannot be used with reversing contactors．
（2）Terminal blocks are supplied with terminals protected against direct finger contact and screws in the open，＂ready－to－tighten＂ position．
（3）To order a terminal block for connection by lugs，the reference becomes LA7 D30646．
（4）Remember to order the terminal block corresponding to the type of relay．
（5）The time for which the coil of remote tripping or electrical resetting device LA7 D03 or LAD 703 can remain energised depends on its rest time： 1 s pulse duration with 9 s rest time； 5 s pulse duration with 30 s rest time； 10 s pulse duration with 90 s rest time；maximum pulse duration 20 s with a rest time of 300 s ．Minimum pulse time： 200 ms ．
（6）Reference to be completed by adding the code indicating the control circuit voltage．
Standard control circuit voltages（for other voltages，please consult your Regional Sales Office）：


Dimensions, mounting

TeSys protection components
TeSys d thermal overload relays

LRD 01... 35
Direct mounting beneath contactors
with screw clamp connections


| LC1 | D09...D18 | D25...D38 |
| :--- | :--- | :--- |
| b | 123 | 137 |
| c | See pages 180 and 181 |  |

LRD 1508... 32
Direct mounting beneath contactors
with screw clamp connections


LRD 013... 223
Direct mounting beneath contactors with spring terminal connections



LRD 3136 ... 3656
Direct mounting beneath contactors LC1 D40A6...D65A6 with lugs


LRD 313 ... 365
Direct mounting beneath contactors LC1 D40A...D65A
with screw clamp connections or EverLink ${ }^{\circledR}$ connectors


| Characteristics: | References: | Schemes: |
| :--- | :--- | :--- |
| page 199 | page 204 | page 213 |

LRD 4•••
Direct mounting beneath contactors LC 1D115 and D150


LRD 01... 35
Independent mounting on $\mathbf{5 0} \mathbf{~ m m}$ centres or on rail AM1 DP200 or DE200


LRD 313 ... 365
Mounting on rail AM1 D•200 or ED200
With terminal block LAD 96560


Panel mounting Outgoing terminal block not shown

LR9 D
Direct mounting beneath contactors LC 1D115 and D150


| AM1 | DP2 |
| :--- | :--- |
| d | 2.5 |



| DP200 and DR200 | DE200 and ED・ャ॰ |
| :--- | :--- |
| 2.5 | 10.5 |


| DP200 and DR200 | DE200 and ED・ャ॰ |
| :--- | :--- |
| 2.5 | 10.5 |

Independent mounting on 110 mm centres


Mounted on plate AM1 P


LRD 01... 35 and LRD 313... 365
Remote tripping or electrical reset


[^3]| Characteristics: | References: | Schemes: |
| :--- | :--- | :--- |
| page 199 | page 204 | page 213 |



LRD，LRD 313．．．365，LRD 15 and LR9 D
＂Reset＂by flexible cable
LA7 D305 and LAD 7305
Mounting with cable straight
Mounting with cable bent

e ：up to 20 mm
c ：up to 550 mm

e ：up to 20 mm

| Characteristics： | References： <br> page 204 | Schemes： <br> page 199 213 |
| :--- | :--- | :--- |

LRD •e，LRD 3eゃ and LR2 D・ゃ


Pre－wiring kit LAD 7C1，LAD 7C2


LR9 D5•••


LR9 D67 and LR9 D69
（2）Overload．
（3）Setting current．


| Characteristics： | References： <br> page 199 | Schemes <br> page 204 |
| :--- | :--- | :--- |

## Motor starters up to 150 A <br> Installation system, power distribution in control panels

TeSys Quickit selection guide ..... page 216■ TeSys Quickfit for motor starter components
$\square$ Presentation ..... page 218
$\square$ Description ..... page 220
$\square$ References ..... page 223
$\square$ Characteristics ..... page 226

- Dimensions ..... page 228
$\square$ Schemes ..... page 230
- Pre-assembled panel busbar system AK5
$\square$ Presentation. ..... page 233
$\square$ Characteristics ..... page 234
$\square$ Mounting: equipment possibilities ..... page 236
- References ..... page 238
$\square$ Dimensions ..... page 240

Selection guide

## Installation system

TeSys Quickfit for motor starter components Components with spring terminals

Assembly and connection of motor starter components with spring terminals, without using tools


Control-command pre-wiring components for TeSys motor circuit-breakers GV2 ME

Type of starter
Coil control
Use with motor starters

## Limited to 60 A (Ith) <br> Limited to 8 starters (1)





## LAD 30

## 223



LAD 9AP3o॰

225
(1) With TeSys circuit-breakers GV2 ME and upstream terminal block LAD $3 B 1$.

Control-command pre-wiring components for TeSys motor circuit-breakers GV3 P


TeSys d (40 to 65A)

| Direct | Reversing |
| :--- | :--- |
| Yes | Yes |
| - |  |
| - |  |
| - |  |

## LU9 G02

225

Parallel interface module, with Advantys STB network interface module


4 starters per module

Modbus Plus, Fipio, CANopen, Ethernet, TCP/IP, Profibus DP, INTERBUS, DeviceNet


## STB EPI2145

225


Motor starter with GV2 ME circuit-breakers


Motor starter with GV3 P circuit-breakers

TeSys Quickfit is a modular system which standardises and simplifies setting up of motor starters with its pre-wired control and power circuits.
Installation of a motor starter is therefore quick, simple, safe and flexible. In addition, this system:

- enables the motor starter to be customised at a later date,
- reduces maintenance time and
- optimises panel space by reducing the number of terminals and intermediate interfaces and the amount of ducting


## System for motor starters with spring terminals

## Motor starters with TeSys GV2 ME circuit-breakers

- From 0 to 18 A max.,
- TeSys GV2 ME circuit-breakers combined with LC1 D contactors from 9 to 25 A (spring terminal version),
■ Quickfit pre-wired power and control connections.


## Motor starters with TeSys GV3 P circuit-breakers

- From 9 to 65 A max.,
- TeSys GV3 P circuit-breakers combined with LC1 D contactors from 40 to 65 A
(spring terminal version),
■ Quickfit pre-wired control connections only,
- For pre-wired power connections, use busbar sets from the TeSys d 40 to 65 A contactor range (see page 173).

This range comprises pre-wiring components for:

- the power circuits,
- the control circuits.


## Power circuit pre-wiring components

(motor starters with TeSys GV2 circuit-breakers only)
■ a power circuit connection kit comprising, for each starter, a plate for mounting the contactor and the circuit-breaker and two power connection modules,

- a power splitter box for 2 or 4 starters,

■ an upstream terminal block for a power supply up to $60 \mathrm{~A}\left(16 \mathrm{~mm}^{2}\right)$,
■ an outgoing terminal block for connection of the motor power supply cables and the earth cables ( $6 \mathrm{~mm}^{2}$ ).

Note: with GV3 circuit-breakers, no accessories are required for pre-wiring of the power circuit. The GV3 P・ゃ outgoing terminal block can be removed.
This circuit-breaker is also sold with only one terminal block (reference: GV3 P $\bullet 1$ ).

Control circuit pre-wiring components
(motor starters with TeSys GV2 and GV3 circuit-breakers)
■ a control circuit connection module which plugs directly into the contactor and the circuit-breaker on each starter. This module incorporates status and control data for this motor starter.

- a parallel wiring module which concentrates the data of each motor starter:
- HE 10 connector, for centralised applications. Data is transmitted to the PLC via the Advantys Telefast pre-wired system.
$\square$ STB, designed for decentralised automation architectures. This module is suitable for use in an Advantys STB configuration for connection to the PLC via a field bus.

| Description: | Characteristics: | References: | Dimensions: |
| :--- | :--- | :--- | :--- |
| page 220 | page 226 | page 223 | page 228 |

1 Automation platform
2 Connection cable TSXCDP＊ゃ or ABFH20॰e
3 Splitter box LU9 G02

4 Network interface module
5 Supply module
6 Parallel interface module

7 TeSys Quickfit module
8 Adapter plate APP 2CX
9 Splitter box LU9 G02 for 8 direct motor starters，with channel connections on the APP 1C module side by two HE 10 connectors（20－way）and on theTeSys Quickfit side，by RJ45 connectors 10 Connection cable APP 2AH40H060

## Control／command <br> HE 10 connection



Connection on bus using Advantys STB（1）
Configuration example（for motor starter applications only）：


| Power supply module |  |
| :---: | :---: |
| Module | STB PDT 3100 |
| Connection base | STB XBA 2200 |
| Terminal block | STB XTB 1130 |
| Parallel interface module（2） |  |
| Module | STB EPI 2145 |
| Connection base | STB XBA 3000 |
| Network interface module（3） |  |
| CANopen | STB NCO 1010 （4） |
| Fipio | STB NFP 2210 |
| Ethernet TCP／IP | STB NIP 2210 |
| InterBus | STB NIB 1010 （4） |
| Profibus DP | STB NDP 1010 （4） |
| DeviceNet | STB NDN 1010 （4） |
| Modbus Plus | STB NMP 2210 |
| Terminal block | STB WTS 2120 |

TeSys Quickfit LAD 9AP3 ゃャ used with modules APP1 C•๑


The motor starter is connected to an APP 1C• module 7 using an adapter plate APP 2CX 8 and a connection cable APP 2AH40H060 10.
Information is available on the module for each motor starter：
－ 1 output：motor control，
■ 2 inputs：circuit－breaker status and contactor status．
（1）Please consult our catalogue＂Advantys STB I／O．The open solution＂．
（2）For 4 direct or 2 reversing motor starters．
（3）Reference to be selected according to the network used．
（4）Optimised version．

| Description： | Characteristics： | References： <br> page 220 | page 223 | Dimensions： |
| :--- | :--- | :--- | :--- | :--- |



## Power components <br> (only for motor starters with TeSys GV2 circuit-breakers) <br> Power kits LAD $3 \bullet$

Each motor starter requires a power kit which consists of a plate 1 and two Quickfit technology power connection modules 2.
The plate is used for mounting TeSys d contactors 3 ( 9 to 25 A , direct or reversing, with spring terminals and fitted with a.c. or d.c. coil) and the GV2 ME circuit-breaker 4 only. This plate is mounted on two $35 \mathrm{~mm} \_$rails or is screwed onto a base plate. The two power connection modules 2 a and 2 b are identical, whatever the rating of the contactor up to 18 A .
The upper power connection module 2a connects the power between the splitter box and the circuit-breaker.
The lower power connection module 2 b connects the power between the circuitbreaker and the contactor.

## Splitter boxes LAD 32•

Splitter boxes 5 are available for 2 or 4 starters.
They can be combined to create motor starters up to 60 A per power supply.
A reversing starter occupies a width equivalent to that of 2 direct starters.
Direct supply of power to the splitter boxes is possible up to $25 \mathrm{~A}\left(4 \mathrm{~mm}^{2}\right)$.

## Upstream terminal block LAD 3B1

The upstream terminal block 6 performs two functions:
■ power supply up to $60 \mathrm{~A}\left(16 \mathrm{~mm}^{2}\right)$,

- power supply between two connected splitter boxes.

The upstream terminal block connects to the splitter box using Quickfit technology. It is positioned on the splitter box or straddling two splitter boxes and takes up a width equivalent to two motor starters.

## Outgoing terminal block LAD 331

The outgoing terminal block 7 performs two functions:
■ connection of the motor power supply cables up to $6 \mathrm{~mm}^{2}$,

- connection of the motor earth cables.

In addition, the terminal block enables quick connection and disconnection for maintenance, avoiding the risk of phase reversal.
The outgoing terminal block connects to the downstream spring terminals on the contactor, using Quickfit technology.

| Presentation: | Characteristics: | References: | Simensions: |
| :--- | :--- | :--- | :--- |
| pages 218 | page 226 | page 223 | page 228 |



## Control/command components <br> Control circuit connection modules LAD 9 AP3 ••

The control circuit connection module 1 plugs directly into the control terminals on the contactor and on the TeSys GV2 ME or TeSys GV3 P motor circuit-breaker, in the location provided for the front-mounting block.
It is compatible with all contactor ratings up to 18 A for TeSys GV2 ME and 65 A for TeSys GV3 P.
Mechanical locking 2 of the system onto the top of the contactor ensures a perfect connection, whatever the operating conditions (vibrations, knocks, etc.).
These modules are available in 4 versions: for direct or reversing starter, with or without contactor coil interface relay.
The coil control can be a.c. or d.c., up to $\sim 250 \mathrm{~V}$ and $-\mathrm{-c} 130 \mathrm{~V}$.
The version without relay is designed to control the contactor coils with no interface, at 24 V d.c.
The version with relay has a connector for connecting the contactor power supply.
Module LAD9 AP3 $\bullet \bullet$ incorporates, in its lower part, several external connectors:
3 RJ45 connector, for connecting the automation system.
4 2-way connector, for connecting the contactor power supply (only on versions with relay).
5 2-way connector, for connecting an external contact in series with the contactor coil (supplied complete with shunt)

## Parallel wiring modules

The parallel wiring system makes it possible to connect motor starters which incorporate TeSys Quickfit technology to the processing unit (PLC) quickly and without any need for tools. The parallel wiring module provides the status and command information for each motor starter.
Control connection modules LAD9 AP3 $\bullet \bullet$ are connected to the parallel wiring modules using RJ45 cables LU9R $\bullet \bullet 6$, which are available in different lengths. The following information is available for each motor starter:

- 2 inputs: circuit-breaker status and contactor status,
- 1 output: contactor coil control.

A direct motor starter uses one RJ45 channel.
A reversing motor starter uses two RJ45 channels.
Note: for motor starters built using TeSys GV3 circuit-breakers and TeSys d contactors, the Quickfit pre-wired system allows the contactor to be mounted below the circuit-breaker or mounting of the two devices side by side.

## Parallel wiring module LU9 G02

This module 7 enables connection of up to 8 direct or 4 reversing motor starters directly to the I/O modules of PLCs. It is used with the Advantys Telefast pre-wiring system (1).
This splitter box is optimised for use with card TSX DMZ28DTK.

## Dedicated parallel interface module STB EPI 2145 (2)

This module enables 4 direct or 2 reversing motor starters to be connected via the Advantys STB distributed I/O solution. With STB network interface modules, motor starters can be connected to the following communication networks: Modbus Plus, FIPIO, CANopen, Ethernet TCP/IP, Profibus DP, INTERBUS and DeviceNet.

[^4]| Presentation: | Characteristics: | References: | Dimensions: |
| :--- | :--- | :--- | :--- |
| page 218 | page 226 | page 223 | page 228 |




| Power circuit pre-wiring components (only for motor starters with TeSys GV2 circuit-breakers) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Description | Maximum connection c.s.a. | Application | Sold in lots of | Reference | Weight kg |
| Upstream terminal block | $16 \mathrm{~mm}^{2}$ (1) | Power supply of 1 or 2 power splitter boxes | 1 | LAD 3B1 | 0.212 |
| Description | Extension by | Number of starters |  | Reference | Weight kg |
| Power splitter box, 60 A | LAD 32• | 2 |  | LAD 322 | 0.120 |
|  |  | 4 |  | LAD 324 | 0.240 |
| Description |  | Composition |  | Reference | Weight kg |
| Direct starter |  |  |  |  |  |
| Power connection kit |  | 1 plate LAD 311 for GV2 ME and <br> 2 power connection modules LAD 341 |  | LAD 352 | 0.078 |



LAD 352
Reversing starter
To build a reversing starter, order 2 kits LAD 352

|  | Maximum <br> connection c.s.a. | Application | Sold in <br> lots of | Reference | Weight <br> kg |
| :--- | :--- | :--- | :--- | :--- | ---: |
| Outgoing terminal block | $6 \mathrm{~mm}^{2}$ | Connection of <br> motor cables | 10 | LAD 331 | 0.050 |
| Description | No. of <br> starters | 1 | Sold in <br> lots of | Unit <br> reference | Weight <br> kg |
| Plate for mounting a <br> GV2 ME circuit-breaker and a contactor | 10 | LAD 311 | 0.042 |  |  |
| Power connection module | 1 | 10 | LAD 341 | 0.018 |  |

(1) Cables with one end pre-crimped are available to allow fast connection. References:

1 set of $3 \times 6 \mathrm{~mm}^{2}$ cables (length 1 m : LAD 3B061, length $2 \mathrm{~m}:$ LAD $3 B 062$ and length $3 \mathrm{~m}:$ LAD 3B063),
1 set of $3 \times 10 \mathrm{~mm}^{2}$ cables (length 1 m : LAD 3B101, length $2 \mathrm{~m}:$ LAD $3 B 102$ and length $3 \mathrm{~m}:$ LAD 3B103),
1 set of $3 \times 16 \mathrm{~mm}^{2}$ cables (length 1 m : LAD 3B161, length $2 \mathrm{~m}:$ LAD 3B162 and length $3 \mathrm{~m}:$ LAD 3B163).


Note: Circuit-breakers TeSys GV3 P and contactors LC1 D40A3 to 65A3 can be mounted side by side, using a set of S-shape busbars (GV3 S).

TeSys Quickfit for motor starter components
Components with spring terminals


| Control-command pre-wiring components |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Description | TeSys d coil voltage | Type of coil control relay | Type of starter | Reference | Weight kg |
| Control connection modules | $\begin{aligned} & \sim 12 \ldots 250 \mathrm{~V} \text { or } \\ & =-5 \ldots 130 \mathrm{~V} \end{aligned}$ | Electromechanical | Direct | LAD 9AP31 | 0.150 |
|  |  |  | Reversing | LAD 9AP32 | 0.200 |
|  | -- 24 V | Without relay | Direct | LAD 9AP3D1 | 0.140 |
|  |  |  | Reversing | LAD 9AP3D2 | 0.190 |
| Parallel wiring modules (--24 V) |  |  |  |  |  |
| Description | Connectors |  |  | Reference | Weight |
|  | PLC side | Motor starter side |  |  | kg |
| Splitter box | $\begin{aligned} & 2 \times \mathrm{HE} 10 \\ & 20 \text {-way } \end{aligned}$ | $8 \times \mathrm{RJ} 45$ |  | LU9 G02 | 0.260 |
| Description | Connectors |  |  | Reference | Weight |
|  | PLC side | Motor starter side |  |  | kg |
| Advantys STB parallel interface module | - | $4 \times \mathrm{RJ} 45$ |  | STB EPI 2145 | 0.165 |


| Connection cables |  |  |  |
| :---: | :---: | :---: | :---: |
| Between the control connection module and the splitter box LU9 G02 or STB EPI 2145 |  |  |  |
| Connectors | Length | Reference | Weight |
|  | m |  | kg |
| $2 \times \mathrm{RJ45}$ connectors | 0.3 | LU9 R03 | 0.045 |
|  | 1 | LU9 R10 | 0.065 |
|  | 3 | LU9 R30 | 0.125 |


| Between splitter box LU9 G02 and the PLC |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Type of connection |  | Gauge | C.s.a. | Length | Reference | Weight |
| PLC side | Splitter box side |  |  |  |  |  |
|  |  | AWG | mm ${ }^{2}$ | m |  | kg |
| HE 10 20-way | HE 10 20-way | 22 | 0.324 | 0.5 | TSX CDP 053 | 0.085 |
|  |  |  |  | 1 | TSX CDP 103 | 0.150 |
|  |  |  |  | 2 | TSX CDP 203 | 0.280 |
|  |  |  |  | 3 | TSX CDP 303 | 0.410 |
|  |  |  |  | 5 | TSX CDP 503 | 0.670 |
|  |  | 28 | 0.080 | 1 | ABF H20 H100 | 0.080 |
|  |  |  |  | 2 | ABF H20 H200 | 0.140 |
|  |  |  |  | 3 | ABF H20 H300 | 0.210 |
| Bare wires | HE 10 | 22 | 0.324 | 3 | TSX CDP 301 | 0.400 |
|  | 20-way |  |  | 5 | TSX CDP 501 | 0.660 |


| Separate components |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Description | Characteristics | Sold in lots of | Unit reference | Weight kg |
| Spring terminal connections for: <br> the external contact <br> the auxiliary power supply | 2-way, 5 mm pitch <br> Wire c.s.a.: $0.2 \ldots 2.5 \mathrm{~mm}^{2}$ | 10 | APE 1PRE21 | 0.020 |
| Self-stripping connector for: <br> the external contact <br> the auxiliary power supply | 2-way, 5 mm pitch Wire c.s.a.: $0.75 \mathrm{~mm}^{2}$ | 16 | APE 1PAD21 | 0.020 |
| Connecting cable between module APP 1C• and splitter box LU9 G02 ( length: 0.6 m) | Connectors: <br> 1 x HE 10, 30-way <br> 2 xHE 10, 20-way | 1 | APP 2AH40H060 | 0.400 |


| Presentation: | Description: | Characteristics: | Schemes: |
| :--- | :--- | :--- | :--- |
| page 218 | page 220 | page 226 | Dimensions: |

## Installation system

TeSys Quickfit for motor starter components Components with spring terminals

| Type of control connection module <br> General environment <br> Standard <br> Certifications |  |  | LAD 9AP3 |
| :--- | :--- | :--- | :--- |


| Presentation: | Description: | References: | Dimensions: |
| :--- | :--- | :--- | :--- |
| pages 218 | pages 220 | pages 223 | pages 228 |


| Circuit-breaker reference | GV2 ratings (1) | Maximum current of GV2 with TeSys Quickfit |
| :---: | :---: | :---: |
| GV2 ME06 | 1-1.6A | 1.28 A |
| GV2 ME07 | 1.6-2.5A | 2 A |
| GV2 ME08 | $2.5-4 \mathrm{~A}$ | 3.2A |
| GV2 ME10 | 4-6.3A | 5A |
| GV2 ME14 | 6-10A | 8A |
| GV2 ME16 | 9-14A | 11.2 A |
| GV2 ME20 | 13-18A | 14.4 A |
| GV2 ME21 | 17-23A | 18 A |

## Electromechanical relay characteristics

| Type of control connection module |  |  | LAD 9AP31, LAD 9AP32 |
| :---: | :---: | :---: | :---: |
| Characteristics of the electromechanical relay control circuit (PLC side) |  |  |  |
| Rated voltage at Us |  | V | -- 24 |
| Energisation threshold at $40^{\circ} \mathrm{C}$ |  | V | --. 19.2 |
| Drop-out voltage at $20^{\circ} \mathrm{C}$ |  | V | -. 2.4 |
| Maximum operational voltage |  | V | -- 30 |
| Maximum current at Us |  | mA | 15 |
| Drop-out current at $20^{\circ} \mathrm{C}$ |  | mA | 1 |
| Maximum power dissipated at Us |  | W | 0.36 |
| Supply failure |  | ms | 5 |
| Characteristics of the electromechanical relay output circuit |  |  |  |
| Type of contact |  |  | 1F |
| Maximum switching voltage |  | V | $\sim 250$ |
|  |  | V | -1 130 |
| Frequency of the operating current |  | Hz | 50/60 |
| Maximum current of the contact |  | A | 4 |
| Other characteristics of the electromechanical relay |  |  |  |
| Maximum operating time at Us (including bounce) | Between coil energisation and closing of the contact | ms | 10 |
|  | Between coil de-energisation and opening of the contact | ms | 5 |
| Maximum operating ratet | No load | Hz | 10 |
|  | Atle | Hz | 0.5 |
| Mechanical life | In millions of operating cycles |  | 20 |
| Dielectric strength |  | V | 1000 ( $50 / 60 \mathrm{~Hz}$ ) - 1 mn |
| Rated impulse withstand voltage (Uimp) |  | kV | 2.5 |
| Primary/secondary rated insulation voltage |  | V | 300 |
| Maximum current for $\mathbf{5 0 0} \mathbf{0 0 0}$ operations | 24 V - DC13 | A | 0.6 |
|  | 230 V - AC15 | A | 0.9 |

(1) Thermal trip setting range.

| Presentation: | Description: | References: | Dimensions: |
| :--- | :--- | :--- | :--- |
| pages 218 | pages 220 | pages 223 | pages 228 |

## Installation system

TeSys Quickfit for motor starter components
Components with spring terminals

## Dimensions

Mounted assembly, with TeSys GV2 ME circuit-breakers and TeSys d contactors


[^5]Mounted assembly with TeSys GV3 P circuit-breakers and TeSys d contactors (LC1 D40A3... LC1 D65A3)

## Vertical mounting

Side by side mounting


2 Set of GV3 G264 busbars
3 Set of S-shape busbars GV3 S

| Presentation: | Description: | Characteristics: | References: |
| :--- | :--- | :--- | :--- |
| page 218 | page 220 | page 226 | page 223 |

Installation system
TeSys Quickfit for motor starter components Components with spring terminals

Dimensions
Parallel wiring modules
Splitter box LU9 G02


Parallel wiring module Advantys STB EPI 2145


## Schemes

Splitter box LU9 G02

Colours of
TSX CDPee
connection cab
wires (4)
1 White
2 Brown
3 Green
4 Yellow
5 Grey
6 Pink
7 Blue
8 Red
9 Black
10 Violet
11 Grey-pink
12 Red-blue
13 White-green
14 Brown-green
15 White-yellow
16 Yellow-brown
17 White-grey
18 Grey-brown
19 White-pink
20 Pink-brown
(2) 20-way HE10 input connector.
(3) 20-way HE10 output connector
(4) Wire colours and corresponding HE10 connector pin numbers.

| Presentation: | Description: | Characteristics: | References: |
| :--- | :--- | :--- | :--- |
| page 218 | page 220 | page 226 | page 223 |

Installation system
TeSys Quickfit for motor starter components Components with spring terminals

## Wiring schemes

## With relay

LAD9 AP31
LAD9 AP32


Q1 Thermal-magnetic motor circuit-breaker.
(1) Contactor coil.
(2) Interface relay.

Installation system
TeSys Quickfit for motor starter components Components with spring terminals

## Wiring schemes (continued)

## Without relay

LAD9 AP3D1


Q1 Thermal-magnetic motor circuit-breaker. (1) Contactor coil.


## Power distribution in control panels Pre-assembled panel busbar system AK5

The assembly of automated control and distribution panels requires the use of products that are not only safe but also simple and quick to mount and cable.

The AK5 pre-assembled busbar system meets all these criteria by incorporating prefabricated components which cater for 3 principal functions:

## Carrying of electric current

By the pre-assembled 4-pole busbar system 1, 160 A at $35^{\circ} \mathrm{C}$.
4-pole busbar systems can be used for 3-phase + Neutral or 3-phase + Common.
The busbar systems are available in 6 lengths: $344,452,560,668,992,1100 \mathrm{~mm}$.
An incoming supply terminal block 2 is located at the extreme left of the busbar system.
"Knock-out" partitions allow connection of the power supply from above or below to connectors 3 which are protected by a removable cover 4.
Upstream protection of the busbar system is shown on page 234.

## Current distribution

Tap-off units 5 (factory assembled) are available in 4 versions:
■ 2-pole,
■ 3-pole,

- 4-pole (3-phase + Neutral),

■ 4-pole (3-phase + Common).
The tap-offs clip onto the busbar system with instantaneous mechanical and electrical connection to the busbars.
2 ratings are available: 16 and 32 A .
The tap-off units ensure not only rapid mounting, but also a neat appearance for the power distribution system and complete safety when accessing under live circuit conditions.

## Component mounting

Component mounting plates with incorporated tap-off allow mounting of and supply of power to components.
They are available in 25 A or 50 A ratings.
These mounting plates clip onto the mounting rail 11, which also supports the busbar system, and at the same time make electrical connection via the incorporated tapoff.

2 types of mounting plate are available:
$■$ single plates 6 (height 105 mm ), with bolt-on 35 mm wide $\_$rail 7 , which may be bolted on in one of two positions, allowing height adjustment of 10 mm .
■ double plates 8 and 14 (height 190 mm ), with two bolt-on, 35 mm wide $\_$rails 9 mounted on 100 mm fixing centres; each rail may be bolted on in one of 4 positions, allowing height adjustment in 10 mm steps. These plates are supplied with connectors 12 to allow wiring between control and protection devices.

Single mounting plates enable the following types of distribution:

- 2-pole ( $\mathrm{Ph}+\mathrm{N}$ ) and ( $\mathrm{Ph}+\mathrm{Ph}$ )
- 3-pole,
- 4-pole (3 Ph + N or $3 \mathrm{Ph}+$ common).

Double mounting plates enable the following types of distribution: 2-pole ( $\mathrm{Ph}+\mathrm{N}$, $\mathrm{Ph}+\mathrm{Ph}$ ), 3-pole or 4 -pole ( $3 \mathrm{Ph}+\mathrm{N}$ and $3 \mathrm{Ph}+$ common).

Extension plates 10 can be bolted onto single and double mounting plates to enable mounting of wider components. Using a side stop 15 in conjunction with these extension plates also supports the AK5 JB busbar system when used vertically.

A control terminal block 13 comprising a support plate bolted onto the single or double mounting plates and a 10-pole plug-in block, enables connection of the control circuit wires (c.s.a. $1.5 \mathrm{~mm}^{2} \mathrm{max}$ ).

## Power distribution in control panels <br> Pre-assembled panel busbar system AK5

| Busbar system characteristics |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Conforming to standards |  |  | IEC 60439 |  |  |  |  |  |  |  |
| Product certifications |  |  | UL, CSA, DNV, LROS |  |  |  |  |  |  |  |
| Degree of protection Against access to live parts |  |  | IP XXB conforming to IEC 60529 |  |  |  |  |  |  |  |
| Flame resistance | Conforming to IEC 60695 | ${ }^{\circ} \mathrm{C}$ | 850 (incandescent wire) |  |  |  |  |  |  |  |
|  | Conforming to standard UL 94 |  | Vo |  |  |  |  |  |  |  |
| Number of conductors AK5 JB14• |  |  | 4 |  |  |  |  |  |  |  |
| Supply current |  |  | $\sim$ |  |  |  |  |  |  |  |
| Rated operational frequency |  | Hz | 50 or 60 |  |  |  |  |  |  |  |
| Rated operational current | Ambient temperature $35^{\circ} \mathrm{C}$ | A | 160 |  |  |  |  |  |  |  |
|  | Coefficient $K$ to be applied according to the ambient temperature | ${ }^{\circ} \mathrm{C}$ | 35 | 40 |  | 45 | 50 | 55 |  | 60 |
|  |  | K | 1 | 0.96 |  | 0.92 | 0.88 | 0.83 |  | 0.78 |
| Rated insulation voltage | Conforming to IEC 60439-1 | V | 690 |  |  |  |  |  |  |  |
|  | Conforming to UL and CSA | V | 600 |  |  |  |  |  |  |  |
| Operational voltage |  |  | Off-load plugging-in and unplugging, with supply switched on$400$ |  |  |  |  |  |  |  |
|  | Conforming to UL, CSA | V | 480 |  |  |  |  |  |  |  |
|  | Conforming to IEC 60439-1 | V | $\begin{array}{\|l\|} \hline \text { Plugging-in } \\ 690 \\ \hline \end{array}$ | nd un | uggin | with sup | witched |  |  |  |
|  | Conforming to UL, CSA | V | 600 |  |  |  |  |  |  |  |
| Maximum permissible peak current |  | kA | 25 |  |  |  |  |  |  |  |
| Maximum let-through energy |  | $A^{2} \mathrm{~s}$ | $1 \times 10^{7}$ |  |  |  |  |  |  |  |
| Upstream short-circuit (1) and overload protection | Type of protection |  | Merlin Gerin circuit-breaker |  |  |  | Fuses |  |  |  |
|  |  |  | NS 160 H |  | NS 160 H |  | aM |  | gF |  |
|  | Rating | A | 160 |  | 160 |  | 160 |  | 160 |  |
|  | Prospective short-circuit current | kA | 36 |  | 70 |  | 100 |  | 100 |  |
|  | Operational current | A | 160 |  | 160 |  | 160 |  | 160 |  |
| Cabling |  |  | Maximum c.s.a. |  |  |  | Minimum c.s.a. |  |  |  |
|  | Flexible cable with cable end | $\mathrm{mm}^{2}$ | 70 |  |  |  | 2.5 |  |  |  |
|  | Solid cable | $\mathrm{mm}^{2}$ | 70 |  |  |  | 2.5 |  |  |  |
|  | Tightening torque | Nm | 10 |  |  |  |  |  |  |  |
| Mounting position | Horizontal or vertical (2) |  | Fixing with | rews | ovide |  |  |  |  |  |
|  |  | (1) For conditions where conditional short-circuit current exceeds 25 kA . <br> (2) Using side stop AK5 BT01 on mounting plates AK5 PA. |  |  |  |  |  |  |  |  |


| Présentation: <br> page 233 | References: <br> page 238 | Dimensions: <br> page 240 |
| :--- | :--- | :--- | | Mounting possibilities: |
| :--- |
| page 236 |



Mounting (equipment possibilities)

## Power distribution in control panels

Pre-assembled panel busbar system AK5


| Note 1: if the equipment is wider than th mounting plate, an extension plate can $b$ used to increase the width of the support plate. <br> Note 2: for upstream protection, see pag 13230/4 <br> (1) 3-pole + common |  | Component mounting plates incorporating tap-off mounted on AK5 JB busbar system |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | AK5 <br> PA211N1 <br> PA211N2 <br> PA211N3 | $\begin{array}{\|l\|} \hline \text { AK5 } \\ \text { PA231 } \\ \text { PA2311 } \end{array}$ (1) | $\begin{array}{\|l\|} \hline \text { AK5 } \\ \text { PA241 } \\ \hline \end{array}$ | AK5 <br> PA212N1 <br> PA212N2 <br> PA212N3 | AK5 <br> PA212PH12 <br> PA213PH13 <br> PA212PH23 | $\begin{array}{\|l\|} \hline \text { AK5PA } \\ 232 \\ \text { PA2312 } \\ \text { (1) } \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline \text { AK5 } \\ \text { PA242 } \end{array}$ | AK5 <br> PA232S <br> PA2312S <br> (1) | AK <br> PA532 <br> PA5312 <br> (1) | $\begin{array}{\|l\|} \hline \text { AK5 } \\ \text { PA542 } \\ \hline \end{array}$ |
| Mounting Width in mm |  | 54 | 54 | 54 | 54 | 54 | 54 | 54 | 108 | 108 | 108 |
| plate Height in mm |  | 105 | 105 | 105 | 190 | 190 | 190 | 190 | 190 | 190 | 190 |
| incorporating tap-off |  | 3 | 3 | 3 | 3 | 3 | 3 | 4 | 6 | 6 | 6 |
| tap-of Thermal curren |  | 25A | 25A | 25A | 25A | 25A | 25A | 25A | 25A | 50 A | 50 A |
| Application |  | Ph + N | 3-pole | $\begin{aligned} & \text { 3-pole } \\ & +\mathrm{N} \\ & \hline \end{aligned}$ | Ph + N | $\mathrm{Ph}+\mathrm{Ph}$ | 3-pole | $\begin{aligned} & \text { 3-pole } \\ & +\mathrm{N} \end{aligned}$ | 3-pole | 3-pole | $\begin{aligned} & \text { 3-pole } \\ & +\mathrm{N} \end{aligned}$ |
| Motor starter type | Minimum centres with 60 mm ducting | Number of points used on the busbar system |  |  |  |  |  |  |  |  |  |
| Motor circuit-breaker (type 1 coordination) |  |  |  |  |  |  |  |  |  |  |  |
| GV2•06 to •22 | 170 | - | 3 | - | - |  |  |  | - | - |  |
| GV3M01 to M40 | 270 | - | - | - | - |  |  |  | - | 6 |  |
| Motor circuit-breaker + contactor |  |  |  |  |  |  |  |  |  |  |  |
| GV2•06 to •16 + LC1 D09 or D12 with 1 add-on block LA8 D | 270 | - | - | - | 4 |  |  |  | - | - |  |
| $\begin{aligned} & \text { GV2•06 to •20 + LC1 D09 } \\ & \text { to D18 } \end{aligned}$ | 270 | - | - | - | 3 |  |  |  | - | - |  |
| GV2•06 to •22 + LC1 D09 or D12 with 1 add-on block LA8 D | 270 | - | - | - | 4 |  |  |  | - | - |  |
| GV3M01 to M40 with GV1A•• + LC1D09 to D32 | 270 | - | - | - | - |  |  |  | - | 7 |  |
| GV3M01 to M40 + LC1 D09 to D32 with 1 add-on block LA8 D | 270 | - | - | - | - |  |  |  | - | 8 |  |
| Motor circuit-breaker + reversing contactor |  |  |  |  |  |  |  |  |  |  |  |
| GV2•06 to •20 + LC2-D09 to D18 with or without add-on block LA8 D | 270 | - | - | - | - |  |  |  | 6 | - |  |
| GV2•22 with 1 add-on block LA8-D | 270 | - | - | - | - |  |  |  | 7 | - |  |
| Integral contactor breaker + protection module |  |  |  |  |  |  |  |  |  |  |  |
| LD1 LB030 + LB1 LB03P•• (integral 18) | 270 | - | 3 | - | - |  |  |  | - | - |  |
| LD1 LB030 with 2 add-on blocks LA1 -LB + LB1 LB30P (integral 18) | 270 | - | 4 | - | - |  |  |  | - | - |  |
| LD1 LB030 with 4 add-on blocks LA1 LB + LB1 LB03P (integral 18) | 270 | - | - | - | - |  |  |  | 6 | - |  |
| $\begin{aligned} & \text { LD1 LC030 + LB1 LC03M } \\ & \text { (integral 32) } \end{aligned}$ | 270 | - | - | - | - |  |  |  | - | 6 |  |
| LD1 LC030 + LB1 LC03M (integral 32) with 1 add-on block LA1 LC and 1 reset device LA1 LC052• | 270 | - | - | - | - |  |  |  | - | 7 |  |
| LD1 LC030 with 2 add-on blocks LA1 LB + LB1 LC03M (integral 32) | 270 | - | - | - | - |  |  |  | - | 6 |  |
| Reversing contactor breaker integral 18 + protection module |  |  |  |  |  |  |  |  |  |  |  |
| LD5 LB130 + LB1 LB03P•• LD5 LB130 with 3 add-on blocks LA1 LB + LB1 LB03P | 270 | - | - | - | - |  |  |  | 6 | - |  |
|  | 270 | - | - | - | - |  |  |  | 8 | - |  |
| Merlin Gerin C 60 circuit-breaker for circuit protection |  |  |  |  |  |  |  |  |  |  |  |
| 2369• | 170 | 2 | - | - | 2 | 2 | - | - | - | - | - |
| 2370• | 170 | - | 3 | - | - | - | 3 | - | 3 | 3 | - |
| 2371• and 2372• | 170 | - | - | 4 | - | - | - | 4 | - | - | 4 |

## Power distribution in control panels <br> Pre-assembled panel busbar system AK5



Omega rail, width 75 mm
This rail is designed to accommodate the busbar system when it is used with AK5 PA mounting plates incorporating tapoffs. It supportsthe busbar system. The plates simply clip onto the rail.

| Material and surface treatment | Depth | Length | Sold in lots of | Unit reference | Weight |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | mm | mm |  |  | kg |
| 2 mm sheet steel | 15 | 2000 (4) | 6 | AM1 DL201 | 3.000 |



| Removable power sockets <br> Use <br> Number of points <br> used on the <br> busbar system | Thermal <br> current | Cable <br> lengths | Sold in <br> lots of | Unit <br> reference | Weight |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | A | mm |  |  |  |  |
| Single-phase <br> + | 1 | 16 | 200 | $6(2)$ | AK5 PC12 | 0.035 |
| Neutral |  | 32 | 1000 | 6 (2) | AK5 PC32L | 0.040 |
| 2-phase | 1 | 16 | 200 | $6(3)$ | AK5 PC12PH | 0.035 |

(1) 4-pole: 3-phase + Neutral or 3-phase + Common.
(2) Total of 6 sockets supplied: 2 sockets $(N+L 1), 2$ sockets $(N+L 2) .2$ sockets $(N+L 3)$.
(3) Total of 6 sockets supplied: 2 sockets ( $L 1+L 2$ ), 2 sockets ( $L 1+L 3$ ). 2 sockets $(L 2+L 3)$.
(4) Cut and drill to suit use.

| Presentation: | Characteristics: | Dimensions: |
| :--- | :--- | :--- |
| page 233 | page 234 | Mounting possibilities: |

## Power distribution in control panels <br> Pre-assembled panel busbar system AK5



AK5 PA231


Component mounting plates incorporating tap-off
Single plate (height 105 mm )

| Use | No. of 18mm <br> points used on the <br> busbar system | Phase | Thermal <br> currentA | Number of <br> rails for com- <br> ponent support | Reference | Weight |
| :--- | :--- | :--- | :--- | :--- | :--- | ---: | ---: |
| Single-phase <br> + neutral | 3 | $\mathrm{Ph} 1+\mathrm{N}$ | 25 | 1 | AK5 PA211N1 | 0.135 |

Double plate (height 190 mm )
Prefabricated 25 A connectors are supplied for connecting the 2 protection and control devices.

| Single-phase + neutral | 3 | Ph1+N | 25 | 2 | AK5 PA212N1 | 0.135 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ph2+N | 25 | 2 | AK5 PA212N2 | 0.135 |
|  |  | Ph3+N | 25 | 2 | AK5 PA212N3 | 0.135 |
| 2-phase | 3 | Ph1+Ph2 | 25 | 2 | AK5 PA212PH12 | 0.135 |
|  |  | Ph1+Ph3 | 25 | 2 | AK5 PA212PH13 | 0.135 |
|  |  | Ph2+Ph3 | 25 | 2 | AK5 PA212PH23 | 0.135 |
| 3-phase | 3 | - | 25 | 2 | AK5 PA232 | 0.230 |
|  | 6 | - | 25 | 2 | AK5 PA232S | 0.600 |
|  |  |  | 50 | 1 | AK5 PA532 | 0.700 |
| 3-phase + neutral | 3 | - | 25 | 2 | AK5 PA242 | 0.230 |
| 3-phase + common | 3 | - | 25 (10 common) | 2 | AK5 PA2312 | 0.235 |
|  | 6 | - | 25 (10 common) | 2 | AK5 PA2312S | 0.610 |
|  |  |  | 50 (10 common) | 1 | AK5 PA5312 | 0.710 |
| 3-phase + neutral | 6 | - | 50 | 1 | AK5 PA542 | 0.715 |

## Extension plates

These plates bolt onto the equipment support plates, after having removed them from the rails, to be able to mount wider components.

| Use | Number of tap-offs <br> at 18 mm intervals | Reference | Weight <br> kg |  |
| :--- | :--- | :--- | :--- | ---: | ---: |
| For mounting <br> plates incor- <br> porating tap-off | Single | 4 | AK5 PE17 | 0.100 |
| Double | 4 | AK5 PE27 | 0.150 |  |
| Side stop (AK5 JB mounted vertically)  | Sold in <br> lots of | Unit <br> reference | Weight <br> kg |  |
| Use | 50 | AK5 BT01 | 0.005 |  |

Control terminal blocks

| Description | Thermal <br> current A | Sold in <br> lots of | Unit <br> reference | Weight <br> kg |
| :--- | :--- | :--- | :--- | ---: |
| 10-pole terminal blocks, for screwing onto plate AK5 PA $\bullet \bullet$ | 10 | AK5 SB1 | 0.065 |  |


| 10-pole front connecting plug-in terminal blocks which can be clipped onto 25 | 10 | rails |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Fixed part | 10 | 10 | AB1 DV10235U | 0.047 |
| Moving part | 10 | AB1 DVM10235U | 0.021 |  |


| Accessories | Marking | Sold in <br> lots of | Unit <br> reference | Weight <br> kg |
| :--- | :--- | :--- | :--- | ---: | ---: |
| Description | $0 \ldots 9$ | 25 | AB1 R• (1) | 0.050 |
| Strips of clip-in markers | + | 25 | AB1 R12 | 0.050 |
| 10 identical numbers, signs or <br> capital letters per strip | - | 25 | AB1 R13 | 0.050 |

(1) Replace the $\bullet$ in the selected reference with the number or letter required. Example: AB1 R1 or AB1 GA.

| Presentation: | Characteristics: | Dimensions: |
| :--- | :--- | :--- |
| page 233 | page 234 | page 240 |

Busbar systems
AK5 JBeゃ・



Busbar feed units
AK5 JBe••


Removable power sockets 16 and 32 A AK5 PC12e．AK5 PC32L•

Installation of AK5 JBeゃゃ busbar systems
Connection
（1）Maximum c．s．a．or connection of conductor without cable end．
Mounting plates incorporating tap－offs， 25 A
AK5 PA2•1．AK5 PA2311．AK5 PA211••••
Single width extension plates AK5 PE17


Note：It is recommended that the power sockets or the removable plates are connected as close as possible to the busbar feed unit．
（1）Can be fixed at 43 mm

| Presentation： | Characteristics： | References： | page 238 |
| :--- | :--- | :--- | :--- |
| page 233 | page 234 | Mounting possibilities： |  |



Component mounting plates incorporating tap-off AK5 PA232S. AK5 PA2312S

AK5 PA532. AK5 PA5312. AK5 PA542


Side stop
AK5 BT01

Control terminal block AK5 SB1


[^6]
## Motor starters up to 150 A <br> Technical information

- Contactors: definitions and comments ..... page 244
- Product standards and certifications. page 246- Tests according to standard utilisation categoriesconforming to IEC 60947-4-1 and 5-1page 248
- Current of asynchronous squirrel cage motorsat nominal load.page 249
■ Contactors: long distance remote control ..... page 250

| Altitude | The rarefied atmosphere at high altitude reduces the dielectric strength of the air and hence the rated operational voltage of the contactor. It also reduces the cooling effect of the air and hence the rated operational current of the contactor (unless the temperature drops at the same time). <br> No derating is necessary up to 3000 m . <br> Derating factors to be applied above this altitude for main pole operational voltage and current (a.c. supply) are as follows. |
| :---: | :---: |
|  | Altitude $3500 \mathrm{~m} \quad 4000 \mathrm{~m} \quad 4500 \mathrm{~m} \quad 5000 \mathrm{~m}$ |
|  | $\begin{array}{lllll}\text { Rated operetional voltage } & 0,90 & 0,80 & 0,70 & 0,60\end{array}$ |
|  | $\begin{array}{lllll}\text { Rated operational current } & 0,92 & 0,90 & 0,88 & 0,86\end{array}$ |
| Ambient air temperature | The temperature of the air surrounding the device, measured near to the device. The operating characteristics are given : <br> - with no restriction for temperatures between - 5 and $+55^{\circ} \mathrm{C}$, <br> - with restrictions, if necessary, for temperatures between - 50 and $+70{ }^{\circ} \mathrm{C}$. |
| Rated operational current (le) | This is defined taking into account the rated operational voltage, operating rate and duty, utilisation category and ambient temperature around the device. |
| Rated conventional thermal current (Ith) (1) | The current which a closed contactor can sustain for a minimum of 8 hours without its temperature rise exceeding the limits given in the standards. |
| Permissible short time rating | The current which a closed contactor can sustain for a short time after a period of no load, without dangerous overheating. |
| Rated operational voltage (Ue) | This is the voltage value which, in conjunction with the rated operational current, determines the use of the contactor or starter, and on which the corresponding tests and the utilisation category are based. For 3-phase circuits it is expressed as the voltage between phases. <br> Apart from exceptional cases such as rotor short-circuiting, the rated operational voltage Ue is less than or equal to the rated insulation voltage Ui. |
| Rated control circuit voltage (Uc) | The rated value of the control circuit voltage, on which the operating characteristics are based. For a.c. applications, the values are given for a near sinusoidal wave form (less than $5 \%$ total harmonic distortion). |
| Rated insulation voltage (Ui) | This is the voltage value used to define the insulation characteristics of a device and referred to in dielectric tests determining leakage paths and creepage distances. As the specifications are not identical for all standards, the rated value given for each of them is not necessarily the same. |
| Rated impulse withstand voltage (Uimp) | The peak value of a voltage surge which the device is able to withstand without breaking down. |
| Rated operational power (expressed in kW) | The rated power of the standard motor which can be switched by the contactor, at the stated operational voltage. |
| Rated breaking capacity (2) | This is the current value which the contactor can break in accordance with the breaking conditions specified in the IEC standard. |
| Rated making capacity (2) | This is the current value which the contactor can make in accordance with the making conditions specified in the IEC standard. |
| On-load factor (m) | This is the ratio between the time the current flows ( t ) and the duration of the cycle ( T ) $\mathrm{m}=\frac{\mathrm{t}}{\mathrm{~T}}$ <br> Cycle duration: duration of current flow + time at zero current |
| Pole impedance | The impedance of one pole is the sum of the impedance of all the circuit components between the input terminal and the output terminal. <br> The impedance comprises a resistive component $(R)$ and an inductive component $(X=L \omega)$. The total impedance therefore depends on the frequency and is normally given for 50 Hz . This average value is given for the pole at its rated operational current. |
| Electrical durability | This is the average number of on-load operating cycles which the main pole contacts can perform without maintenance. The electrical durability depends on the utilisation category, the rated operational current and the rated operational voltage. |
| Mechanical durability | This is the average number of no-load operating cycles (i.e. with zero current flow through the main poles) which the contactor can perform without mechanical failure. |

(1) Conventional thermal current, in free air, conforming to IEC standards.
(2) For a.c. applications, the breaking and making capacities are expressed by the rms value of the symmetrical component of the short-circuit current. Taking into account the maximum asymmetry which may exist in the circuit, the contacts therefore have to withstand a peak asymmetrical current which may be twice the rms symmetrical component.
Note : these definitions are extracted from standard IEC 60947-1.

| Contactor utilisation categories conforming to IEC 60947-4 |  |
| :---: | :---: |
|  | The standard utilisation categories define the current values which the contactor must be able to make or break. <br> These values depend on: <br> - the type of load being switched : squirrel cage or slip ring motor, resistors, <br> - the conditions under which making or breaking takes place: motor stalled, starting or running, reversing, plugging. |
| a.c. applications |  |
| Category AC-1 | This category applies to all types of a.c. load with a power factor equal to or greater than 0.95 ( $\cos \varphi \geqslant 0.95$ ). <br> Application examples: heating, distribution. |
| Category AC-2 | This category applies to starting, plugging and inching of slip ring motors. On closing, the contactor makes the starting current, which is about 2.5 times the rated current of the motor. <br> On opening, it must break the starting current, at a voltage less than or equal to the mains supply voltage. |
| Category AC-3 | This category applies to squirrel cage motors with breaking during normal running of the motor. On closing, the contactor makes the starting current, which is about 5 to 7 times the rated current of the motor. <br> On opening, it breaks the rated current drawn by the motor; at this point, the voltage at the contactor terminals is about $20 \%$ of the mains supply voltage. Breaking is light. <br> Application examples: all standard squirrel cage motors: lifts, escalators, conveyor belts, bucket elevators, compressors, pumps, mixers, air conditioning units, etc... . |
| Category AC-4 | This category covers applications with plugging and inching of squirrel cage and slip ring motors. The contactor closes at a current peak which may be as high as 5 or 7 times the rated motor current. On opening it breaks this same current at a voltage which is higher, the lower the motor speed. This voltage can be the same as the mains voltage. Breaking is severe <br> Application examples: printing machines, wire drawing machines, cranes and hoists, metallurgy industry. |
| d.c. applications |  |
| Category DC-1 | This category applies to all types of d.c. load with a time constant (L/R) of less than or equal to 1 ms . |
| Category DC-3 | This category applies to starting, counter-current braking and inching of shunt motors. Time constant $\leqslant 2 \mathrm{~ms}$. <br> On closing, the contactor makes the starting current, which is about 2.5 times the rated motor current. <br> On opening, the contactor must be able to break 2.5 times the starting current at a voltage which is less than or equal to the mains voltage. The slower the motor speed, and therefore the lower its back e.m.f., the higher this voltage. Breaking is difficult. |
| Category DC-5 | This category applies to starting, counter-current braking and inching of series wound motors. Time constant $\leqslant 7.5 \mathrm{~ms}$. <br> On closing, the contactor makes a starting current peak which may be as high as 2.5 times the rated motor current. On opening, the contactor breaks this same current at a voltage which is higher, the lower the motor speed. This voltage can be the same as the mains voltage. Breaking is severe. |
| Utilisation categories for auxiliary contacts \& control relays conforming to IEC 60947-5 |  |
| a.c. applications |  |
| Category AC-14 (1) | This category applies to the switching of electromagnetic loads whose power drawn with the electromagnet closed is less than 72 VA. <br> Application example: switching the operating coil of contactors and relays. |
| Category AC-15 (1) | This category applies to the switching of electromagnetic loads whose power drawn with the electromagnet closed is more 72 VA . <br> Application example: switching the operating coil of contactors. |
| d.c. applications |  |
| Category DC-13 (2) | This category applies to the switching of electromagnetic loads for which the time taken to reach $95 \%$ of the steady state current ( $T=0.95$ ) is equal to 6 times the power $P$ drawn by the load (with $P \leqslant 50 W$ ). <br> Application example: switching the operating coil of contactors without economy resistor. |

(1) Replaces category AC-11.
(2) Replaces category DC-13.

## Standardisation

## Conformity to standards

Telemecanique brand products satisfy, in the majority of cases, national (for example: BS in Great Britain, NF in France, DIN in Germany), European (for example: CENELEC) or international (IEC) standards. These product standards precisely define the performance of the designated products (such as IEC 60947 for low voltage equipment).
When used correctly, as designated by the manufacturer and in accordance with regulations and correct practices, these products will allow users to build equipment, machine systems or installations that conform to their appropriate standards (for example: IEC 60204-1, relating to electrical equipment used on industrial machines).
Schneider Electric is able to provide proof of conformity of its production to the standards it has chosen to comply with, through its quality assurance system.
On request, and depending on the situation, Schneider Electric can provide the following:

- a declaration of conformity,
- a certificate of conformity (ASEFA/LOVAG),
- a homologation certificate or approval, in the countries where this procedure is required or for particular specifications, such as those existing in the merchant navy.

| Code | Certification authority |  | Country |
| :--- | :--- | :--- | :--- |
|  | Name | Abbreviation |  |
| ANSI | American National Standards Institute | ANSI | USA |
| BS | British Standards Institution | BSI | Great Britain |
| CEI | Comitato Elettrotecnico Italiano | CEI | Italy |
| DIN/VDE | Verband Deutscher Electrotechniker | VDE | Germany |
| EN | Comité Européen de Normalisation Electrotechnique | CENELEC | Europe |
| GOST | Gosudarstvenne Komitet Standartov | GOST | Russia |
| IEC | International Electrotechnical Commission | IEC | Worldwide |
| JIS | Japanese Industrial Standard | JISC | Japan |
| NBN | Institut Belge de Normalisation | IBN | Belgium |
| NEN | Nederlands Normalisatie Institut | NNI | Netherlands |
| NF | Union Technique de l'Electricité | UTE | France |
| SAA | Standards Association of Australia | SAA | Australia |
| UNE | Asociacion Española de Normalizacion y Certificacion | AENOR | Spain |

## European EN standards

These are technical specifications established in conjunction with, and with approval of, the relative bodies within the various CENELEC member countries (European Union, European Free Trade Association and many central and eastern European countries having «member» or «affiliated» status). Prepared in accordance with the principle of consensus, the European standards are the result of a weighted majority vote. Such adopted standards are then integrated into the national collection of standards, and contradictory national standards are withdrawn. European standards incorporated within the French collection of standards carry the prefix NF EN. At the 'Union Technique de l'Electricité' (Technical Union of Electricity) (UTE), the French version of a corresponding European standard carries a dual number: European reference (NF EN ...) and classification index (C ...).
Therefore, the standard NF EN 60947-4-1 relating to motor contactors and starters, effectively constitutes the French version of the European standard EN 60947-4-1 and carries the UTE classification C 63-110.
This standard is identical to the British standard BS EN 60947-4-1 or the German standard DIN EN 60947-4-1.
Whenever reasonably practical, European standards reflect the international standards (IEC). With regard to automation system components and distribution equipment, in addition to complying with the requirements of French NF standards, Telemecanique brand components conform to the standards of all other major industrial countries.

## Regulations

## European Directives

Opening up of European markets assumes harmonisation of the regulations pertaining to each of the member countries of the European Union.
The purpose of the European Directive is to eliminate obstacles hindering the free circulation of goods within the European Union, and it must be applied in all member countries. Member countries are obliged to transcribe each Directive into their national legislation and to simultaneously withdraw any contradictory regulations. The Directives, in particular those of a technical nature which concern us, only establish the objectives to be achieved, referred to as "essential requirements".
The manufacturer must take all the necessary measures to ensure that his products conform to the requirements of each Directive applicable to his production.
As a general rule, the manufacturer certifies conformity to the essential requirements of the Directive(s) for his product by affixing the C $\in$ mark.
The C $€$ mark is affixed to Telemecanique brand products concerned, in order to comply with French and European regulations.

## Significance of the C $\in$ mark

- The C $\in$ mark affixed to a product signifies that the manufacturer certifies that the product conforms to the relevant European Directive(s) which concern it; this condition must be met to allow free distribution and circulation within the countries of the European Union of any product subject to one or more of the E.U. Directives.
- The C $\epsilon$ mark is intended solely for national market control authorities.
- The C $\in$ mark must not be confused with a conformity marking.


## European Directives (continued)

For electrical equipment, only conformity to standards signifies that the product is suitable for its designated function, and only the guarantee of an established manufacturer can provide a high level of quality assurance.
For Telemecanique brand products, one or several Directives are likely to be applicable,
depending on the product, and in particular:

- the Low Voltage Directive 73/23/EEC amended by Directive 93/68/EEC: the C $\in$ mark relating to this Directive has been compulsory since 1st January 1997.
- the Electromagnetic Compatibility Directive 89/336/EEC, amended by Directives 92/31/EEC and 93/68/EEC: the C $\in$ mark on products covered by this Directive has been compulsory since 1st January 1996


## ASEFA-LOVAG certification

The function of ASEFA (Association des Stations d'Essais Française d'Appareils électriques Association of French Testing Stations for Low Voltage Industrial Electrical Equipment) is to carry out tests of conformity to standards and to issue certificates of conformity and test reports. ASEFA laboratories are authorised by the French authorisation committee (COFRAC). ASEFA is now a member of the European agreement group LOVAG (Low Voltage Agreement Group). This means that any certificates issued by LOVAG/ASEFA are recognised by all the authorities which are members of the group and carry the same validity as those issued by any of the member authorities.

## Quality labels

When components can be used in domestic and similar applications, it is sometimes recommended that a "Quality label" be obtained, which is a form of certification of conformity.

| Code | Quality label | Country |
| :--- | :--- | :--- |
| CEBEC | Comité Electrotechnique Belge | Belgium |
| KEMA-KEUR | Keuring van Electrotechnische Materialen | Netherlands |
| NF | Union Technique de l'Electricité | France |
| ÖVE | Österreichischer Verband für Electrotechnik | Austria |
| SEMKO | Svenska Electriska Materiel Kontrollanatalten | Sweden |

## Product certifications

In some countries, the certification of certain electrical components is a legal requirement. In this case, a certificate of conformity to the standard is issued by the official test authority. Each certified device must bear the relevant certification symbols when these are mandatory:

| Code | Certification authority | Country |
| :--- | :--- | :--- |
| CSA | Canadian Standards Association | Canada |
| UL | Underwriters Laboratories | USA |
| CCC | China Compulsory Certification | China |

Note on certifications issued by the Underwriters Laboratories (UL). There are two levels of approval:
"Recognized" ( 7 )
The component is fully approved for inclusion in equipment built in a workshop, where the operating limits are known by the equipment manufacturer and where its use within such limits is acceptable by the Underwriters Laboratories.
The component is not approved as a "Product for general use" because its manufacturing characteristics are incomplete or its application possibilities are limited.
A "Recognized" component does not necessarily carry the certification symbol.
"Listed" (UL) The component conforms to all the requirements of the classification applicable to it and may therefore be used both as a "Product for general use" and as a component in assembled equipment. A "Listed" component must carry the certification symbol.

## Marine classification societies

Prior approval (= certification) by certain marine classification societies is generally required for electrical equipment which is intended for use on board merchant vessels.

| Code | Classification authority | Country |
| :--- | :--- | :--- |
| BV | Bureau Veritas | France |
| DNV | Det Norske Veritas | Norway |
| GL | Germanischer Lloyd | Germany |
| LR | Lloyd's Register | Great Britain |
| NKK | Nippon Kaiji Kyokaï | Japan |
| RINA | Registro Italiano Navale | Italy |
| RRS | Register of Shipping | Russia |

## Note

For further details on a specific product, please refer to the "Characteristics" pages in this catalogue or consult your Regional Sales Office. conforming to IEC 60947-4-1 and 5-1
based on rated operational current le and rated operational voltage Ue


## Control relays and auxiliary contacts

|  |  | Electrical durability: making and breaking conditions |  |  |  |  |  | Occasional duty: making and breaking conditions |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| a.c. supply |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Typical | Utilisation | Making |  |  | Breaking |  |  | Making |  |  | Breaking |  |  |
| applications |  | I | U | $\boldsymbol{\operatorname { c o s }} \varphi$ | I | U | $\boldsymbol{\operatorname { c o s }} \varphi$ |  | U | $\boldsymbol{\operatorname { c o s }} \varphi$ | I | U | $\boldsymbol{\operatorname { c o s }} \varphi$ |
| Electromagnets |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\leqslant 72 \mathrm{VA}$ | AC-14 | - | - | - | - | - | - | 6 le | 1.1 Ue | 0.7 | 6 le | 1.1 Ue | 0.7 |
| > 72 VA | AC-15 | 10 le | Ue | 0.7 | le | Ue | 0.4 | 10 le | 1.1 Ue | 0.3 | 10 le | 1.1 Ue | 0.3 |


| d.c. supply |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Typical applications | Utilisation category | Making |  |  | Breaking |  |  | Making |  |  | Breaking |  |  |
|  |  | 1 | U | L/R (ms) | 1 | U | L/R (ms) | 1 | U | L/R (ms) | 1 | U | L/R (ms) |
| Electromagnets | DC-13 | le | Ue | 6 P (3) | le | Ue | 6 P (3) | 1.1 le | 1.1 Ue | 6 P (3) | 1.1 le | 1.1 Ue | 6 P (3) |

[^7]Technical information
Current of asynchronous squirrel cage motors at nominal load

## 3-phase 4-pole motors



| Rated operational power (1) | Indicative rated operational current values at: |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 230 V | 400 V | 500 V | 690 V |
| kW | A | A | A | A |
| 0.06 | 0.35 | 0.2 | 0.16 | 0.12 |
| 0.09 | 0.52 | 0.3 | 0.24 | 0.17 |
| 0.12 | 0.7 | 0.44 | 0.32 | 0.23 |
| 0.18 | 1 | 0.6 | 0.48 | 0.35 |
| 0.25 | 1.5 | 0.85 | 0.68 | 0.49 |
| 0.37 | 1.9 | 1.1 | 0.88 | 0.64 |
| 0.55 | 2.6 | 1.5 | 1.2 | 0.87 |
| 0.75 | 3.3 | 1.9 | 1.5 | 1.1 |
| 1.1 | 4.7 | 2.7 | 2.2 | 1.6 |
| 1.5 | 6.3 | 3.6 | 2.9 | 2.1 |
| 2.2 | 8.5 | 4.9 | 3.9 | 2.8 |
| 3 | 11.3 | 6.5 | 5.2 | 3.8 |
| 4 | 15 | 8.5 | 6.8 | 4.9 |
| 5.5 | 20 | 11.5 | 9.2 | 6.7 |
| 7.5 | 27 | 15.5 | 12.4 | 8.9 |
| 11 | 38 | 22 | 17.6 | 12.8 |
| 15 | 51 | 29 | 23 | 17 |
| 18.5 | 61 | 35 | 28 | 21 |
| 22 | 72 | 41 | 33 | 24 |
| 30 | 96 | 55 | 44 | 32 |
| 37 | 115 | 66 | 53 | 39 |
| 45 | 140 | 80 | 64 | 47 |
| 55 | 169 | 97 | 78 | 57 |
| 75 | 230 | 132 | 106 | 77 |
| 90 | 278 | 160 | 128 | 93 |
| 110 | 340 | 195 | 156 | 113 |
| 132 | 400 | 230 | 184 | 134 |
| 160 | 487 | 280 | 224 | 162 |
| 200 | 609 | 350 | 280 | 203 |
| 250 | 748 | 430 | 344 | 250 |
| 315 | 940 | 540 | 432 | 313 |
| 355 | 1061 | 610 | 488 | 354 |
| 400 | 1200 | 690 | 552 | 400 |
| 500 | 1478 | 850 | 680 | 493 |
| 560 | 1652 | 950 | 760 | 551 |
| 630 | 1844 | 1060 | 848 | 615 |
| 710 | 2070 | 1190 | 952 | 690 |
| 800 | 2340 | 1346 | 1076 | 780 |
| 900 | 2640 | 1518 | 1214 | 880 |
| 1000 | 2910 | 1673 | 1339 | 970 |

## Current values for power in hp

| Rated operational power (2) | Indicative rated operational current values at: |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & 110- \\ & 120 \text { V } \end{aligned}$ | 200 V | 208 V | $\begin{aligned} & 220- \\ & 240 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 380- \\ & 415 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 440- \\ & 480 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 550- \\ & 600 \text { V } \end{aligned}$ |
| hp | A | A | A | A | A | A | A |
| 1/2 | 4.4 | 2.5 | 2.4 | 2.2 | 1.3 | 1.1 | 0.9 |
| 3/4 | 6.4 | 3.7 | 3.5 | 3.2 | 1.8 | 1.6 | 1.3 |
| 1 | 8.4 | 4.8 | 4.6 | 4.2 | 2.3 | 2.1 | 1.7 |
| $1^{1 / 2}$ | 12 | 6.9 | 6.6 | 6 | 3.3 | 3 | 2.4 |
| 2 | 13.6 | 7.8 | 7.5 | 6.8 | 4.3 | 3.4 | 2.7 |
| 3 | 19.2 | 11 | 10.6 | 9.6 | 6.1 | 4.8 | 3.9 |
| 5 | 30.4 | 17.5 | 16.7 | 15.2 | 9.7 | 7.6 | 6.1 |
| $7^{1 / 2}$ | 44 | 25.3 | 24.2 | 22 | 14 | 11 | 9 |
| 10 | 56 | 32.2 | 30.8 | 28 | 18 | 14 | 11 |
| 15 | 84 | 48.3 | 46.2 | 42 | 27 | 21 | 17 |
| 20 | 108 | 62.1 | 59.4 | 54 | 34 | 27 | 22 |
| 25 | 136 | 78.2 | 74.8 | 68 | 44 | 34 | 27 |
| 30 | 160 | 92 | 88 | 80 | 51 | 40 | 32 |
| 40 | 208 | 120 | 114 | 104 | 66 | 52 | 41 |
| 50 | 260 | 150 | 143 | 130 | 83 | 65 | 52 |
| 60 | - | 177 | 169 | 154 | 103 | 77 | 62 |
| 75 | - | 221 | 211 | 192 | 128 | 96 | 77 |
| 100 | - | 285 | 273 | 248 | 165 | 124 | 99 |
| 125 | - | 359 | 343 | 312 | 208 | 156 | 125 |
| 150 | - | 414 | 396 | 360 | 240 | 180 | 144 |
| 200 | - | 552 | 528 | 480 | 320 | 240 | 192 |
| 250 | - | - | - | 604 | 403 | 302 | 242 |
| 300 | - | - | - | 722 | 482 | 361 | 289 |
| 350 | - | - | - | 828 | 560 | 414 | 336 |
| 400 | - | - | - | 954 | 636 | 477 | 382 |
| 450 | - | - | - | 1030 | - | 515 | 412 |
| 500 | - | - | - | 1180 | 786 | 590 | 472 |

(1) Values conforming to standard IEC 60072-1 (at 50 Hz ).
(2) Values conforming to standard UL 508 (at 60 Hz ).

Nota : These values are given as a guide. They may vary depending on the type of motor, its polarity and the manufacturer.

## Voltage drop caused by the inrush current

When the operating coil of a contactor is energised, the inrush current produces a voltage drop in the control circuit cable caused by the resistance of the conductors, which can adversely affect closing of the contactor.
An excessive voltage drop in the control supply cables (both a.c. and d.c.) can lead to non closure of the contactor poles or even destruction of the coil due to overheating.
This phenomenon is aggravated by:

- a long line,
- a low control circuit voltage,

■ a cable with a small c.s.a.,

- a high inrush power drawn by the coil.

The maximum length of cable, depending on the control voltage, the inrush power and the conductor c.s.a., is indicated in the graphs below.

## Remedial action

To reduce the voltage drop at switch-on:
■ increase the conductor c.s.a.,

- use a higher control circuit voltage,
- use an intermediate control relay.


## Selection of conductor c.s.a.

These graphs are for a maximum line voltage drop of 5\%. They give a direct indication of the copper conductor c.s.a. to be used for the control cable, depending on its length, the inrush power drawn by the contactor coil and the control circuit voltage (see example page 251).

Total resistance of the 2 conductors in the control cable in $\Omega(1)$


| $1 \sim 24 \mathrm{~V}$ | $3 \sim 115 \mathrm{~V}$ | $5 \sim 400 \mathrm{~V}$ |
| :--- | :--- | :--- |
| $2 \sim 48 \mathrm{~V}$ | $4 \sim 230 \mathrm{~V}$ | $6 \sim 690 \mathrm{~V}$ |

Total resistance of the 2 conductors
in the control cable in $\Omega(1)$


| $7-24 \mathrm{~V}$ | $9-125 \mathrm{~V}$ |
| :--- | :--- |
| $8-48 \mathrm{~V}$ | $10-250 \mathrm{~V}$ |

Total resistance of the 2 conductors in the control cable in $\Omega$ (1)

C.s.a. of copper cables

| A $0.75 \mathrm{~mm}^{2}$ | C $1.5 \mathrm{~mm}^{2}$ | E $4 \mathrm{~mm}^{2}$ |
| :--- | :--- | :--- |
| B $1 \mathrm{~mm}^{2}$ | D $2.5 \mathrm{~mm}^{2}$ | F $6 \mathrm{~mm}^{2}$ |

Total resistance of the 2 conductors

(1) For 3-wire control, the current only flows in 2 of the conductors.
(2) This is the length of the cable comprising 2 or 3 conductors. (Distance between the contactor and the control device).

## TeSys contactors

Long distance remote control

## Voltage drop caused by the inrush current (continued)

What cable c.s.a. is required for the control circuit of an LC1 D40A, 115 V contactor, operated from a distance of 150 metres?

■ Contactor LC1 D40A, voltage 115 V, 50 Hz : inrush power: 200 VA
On the left-hand graph on the page opposite, point $X$ is at the intersection of the vertical line corresponding to 200 VA and the $\sim 115 \mathrm{~V}$ voltage curve.

On the right-hand graph on the page opposite, point $Y$ is at the intersection of the vertical line corresponding to 150 m and the horizontal line passing through point X .

Use the conductor c.s.a. indicated by the curve which passes through point $Y$, i.e.: $1.5 \mathrm{~mm}^{2}$.

If point Y lies between two c.s.a. curves, choose the larger of the c.s.a. values.

## Calculating the maximum cable length

The maximum permissible length for acceptable line voltage drop is calculated by the formula:
$\mathrm{L}=\frac{\mathrm{U}^{2}}{\mathrm{SA}} . \mathrm{s} . \mathrm{K}$
where:
L : distance between the contactor and the control device in $m$ (length of the cable),
U : supply voltage in V ,
SA : apparent inrush power drawn by the coil in VA,
s : conductor c.s.a. in $\mathrm{mm}^{2}$,
K : factor given in the table below.

|  | SA in VA | $\mathbf{2 0}$ | $\mathbf{4 0}$ | $\mathbf{1 0 0}$ | $\mathbf{1 5 0}$ | $\mathbf{2 0 0}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| a.c. supply | K | 1.38 | 1.5 | 1.8 | 2 | 2.15 |
|  |  |  |  |  |  |  |
| d.c. supply | Irrespective of the apparent inrush power SA , expressed in W |  |  |  |  |  |
|  | $\mathrm{K}=1.38$ |  |  |  |  |  |

## TeSys contactors <br> Long distance remote control

## Residual current in the coil due to cable capacitance

When the control contact of a contactor is opened, the control cable capacitance is effectively in series with the coil of the electromagnet. This capacitance can cause a residual current to be maintained in the coil, with the risk that the contactor will remain closed.

## This only applies to contactors operating on an a.c. supply.

This phenomenon is aggravated by:
■ a long line length between the coil control contact and the contactor, or between
the coil control contact and the power supply,
■ a high control circuit voltage,

- a low coil consumption, sealed,
- a low value of contactor drop-out voltage.

The maximum control cable length, according to the contactor coil supply voltage, is indicated in the graph on the page opposite

## Remedial action

Various solutions can be adopted to avoid the risk of the contactor remaining closed due to cable capacitance:

- use a d.c. control voltage, or,
- add a rectifier, connected as shown in the scheme below, but retaining an a.c. operating coil: in this way, rectified a.c. current flows in the control cable.

When calculating the maximum cable length, take the resistance of the conductors into account.


■ Connect a resistor in parallel with the contactor coil (1).
Value of the resistance :
$R \Omega=\frac{1}{10^{-3} \mathrm{C}(\mu \mathrm{F})}$
(C capacitance of the control cable)

Power to be dissipated :
$P W=\frac{U^{2}}{R}$

[^8] operation after the contactor has closed by using an N/O contact.

Residual current in the coil due to cable capacitance (continued)
These graphs are for a capacitance, between 2 conductors, of $0.2 \mu \mathrm{~F} / \mathrm{km}$. They make it possible to determine whether there is a risk of the contactor remaining closed due to the power drawn by the coil when sealed, as well as the control circuit voltage, according to the length of the control cable.



| $1 \sim 24 \mathrm{~V}$ | 3 | $\sim 115 \mathrm{~V}$ | 5 | $\sim 400 \mathrm{~V}$ | 7 | 3-wire control |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $2 \sim 48 \mathrm{~V}$ | 4 | $\sim 230 \mathrm{~V}$ | 6 | $\sim 690 \mathrm{~V}$ | 8 | 2-wire control |

In the zones below the straight lines for 3-wire and 2-wire control respectively, there is a risk of the contactor remaining closed.

## Examples

What is the maximum length for the control cable of an LC1 D12 contactor, operating on 230 V, with 2-wire control?

- Contactor LC1 D12, voltage $230 \mathrm{~V}, 50 \mathrm{~Hz}$ : power sealed 7 VA .

On the left-hand graph, point $A$ is at the intersection of the vertical line for 7 VA with the $\sim 230 \mathrm{~V}$ voltage curve.

On the right-hand graph, point $B$ is at the intersection of the horizontal line with the 2-wire control curve.

The maximum cable length is therefore 300 m .
In the same example, with a 600 m cable, the point lies in the risk zone. A resistor must therefore be connected in parallel with the contactor coil.

Value of this resistance :
$R=\frac{1}{10^{-3} \cdot C}=\frac{1}{10^{-3} \cdot 0.12}=8.3 \Omega$
Power to be dissipated :
$\mathrm{P}=\frac{\mathrm{U}^{2}}{\mathrm{R}}=\frac{(220)^{2}}{8300}=6 \mathrm{~W}$

Alternative solution: use a d.c. control supply.

## Calculating the cable length

The maximum permitted length of control cable to avoid the effects of capacitance is calculated using the formula:
$\mathrm{L}=455 \cdot \frac{\mathrm{~S}}{\mathrm{U}^{2} . \mathrm{Co}}$

L : distance between the contactor and the control device in km (length of the cable),
S : apparent power, sealed, in VA,
U : control voltage in V ,
Co : line capacitance of the cable in $\mu \mathrm{F} / \mathrm{km}$.

| Thermal-magnetic motor circuit-breakers GV3 ME |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Old reference | Icu / 400 V | New reference | Icu / 400 V | Ir |
| GV3 ME06 | 100 kA | GV2 P06 | $>100 \mathrm{kA}$ | 1...1.6A |
| GV3 ME07 | 100 kA | GV2 P07 | $>100 \mathrm{kA}$ | 1.6...2.5A |
| GV3 ME08 | 100 kA | GV2 P08 | $>100 \mathrm{kA}$ | 2.5...4A |
| GV3 ME10 | 100 kA | GV2 P10 | $>100 \mathrm{kA}$ | 4...6 A |
| GV3 ME14 | 100 kA | GV2 P14 | $>100 \mathrm{kA}$ | 6...10 A |
| GV3 ME20 | 100 kA | GV3 P13 | 100 kA | 9...13 A |
|  |  | GV3 P18 | 100 kA | 12...18A |
| GV3 ME25 | 100 kA | GV3 P25 | 100 kA | 17...25A |
| GV3 ME40 | 35 kA | GV3 P32 | 100 kA | 23...32A |
|  |  | GV3 P40 | 50 kA | 30...40 A |
| GV3 ME63 | 35 kA | GV3 P50 | 50 kA | 37...50 A |
|  |  | GV3 P65 | 50 kA | 48...65A |

Magnetic motor circuit-breakers GK3 EF

| Old reference | Icu / 400 V | New reference | Icu / 400 V | le |
| :---: | :---: | :---: | :---: | :---: |
| GK3 EF40 | 50 kA | GV3 L25 | 100 kA | 25A |
|  |  | GV3 L32 | 100 kA | 32 A |
|  |  | GV3 L40 | 50 kA | 40 A |
| GK3 EF65 | 35 kA | GV3 L50 | 50 kA | 50 A |
|  |  | GV3 L65 | 50 kA | 65 A |
| Enclosed motor circuit-breakers GV3 ME |  |  |  |  |
| Old reference | Type of operator (not included) | New reference | Type of han |  |
| GV3 CE01 | GV1K0• | GV3 PC01 | LU9 AP11 (bla |  |

## Contact blocks (1)

| Old reference | For circuit-breaker | N |
| :---: | :---: | :---: |
| GV3 A01 | GV3 ME | G |
| GV3 A02 | GV3 ME | G |
| GV3A03 | GV3 ME | G |
| GV3 A05 | GV3 ME | G |
| GV3 A06 | GV3 ME |  |
| GV3 A07 | GV3 ME |  |
| GV3 A08 | GV3 ME | , |
| GV3 A09 | GV3 ME |  |
| GK2 AX10 | GK3 EF | G |
| GK2 AX20 | GK3 EF | G |
| GK2 AX50 | GK3 EF | G |
| GK2 AX12 | GK3 EF | G |
| GK2 AX22 | GK3 EF | - |
| GK2 AX52 | GK3 EF | - |


| New reference | For circuit-breaker |
| :--- | :--- |
| GV AE11 or GV AN11 | GV2, GV3 P and GV3 L |
| GV AE20 or GV AN20 | GV2, GV3 P and GV3 L |
| GV AE1 + GV AN20 | GV2, GV3 P and GV3 L |
| GV AE1 + GV AN20 | GV2, GV3 P and GV3 L |
| - | - |
| - | - |
| GVA D0110 or GVA D0101 | GV2, GV3 P and GV3 L |
| GVA D1010 or GVA D1001 | GV2, GV3 P and GV3L |
| GVA ED101 or GVA ED011 | GV3 P and GV3 L |
| GVA E1 | GV2, GV3 P and GV3 L |
| GVA E20 or GVA N20 | GV2, GV3 P and GV3L |
| GVA E11 or GVA N11 | GV2, GV3 P and GV3L |
| GVA D1010 or GVA D1001 | GV2, GV3 P and GV3L |
| GVA ED101 or GVAED011 | GV2, GV3 P and GV3L |
| - | - |
| - | - |

Electric trips (1)

| Old reference | For circuit-breaker | New reference | For circuit-breaker |
| :--- | :--- | :--- | :--- |
| GV3 B11 $(50 \mathrm{~Hz})$ | GV3 ME | GVA U115 or GVA U125 | GV2, GV3 P and GV3 L |
| GV3 B11 $(60 \mathrm{~Hz})$ | GV3 ME | GVA U115 | GV2, GV3 P and GV3 |
| GV3 B22 $(50 \mathrm{~Hz})$ | GV3 ME | GVA U225 | GV2, GV3 P and GV3 L |
| GV3 B38 | GV3 ME | GVA U385 or GVA U415 | GV2, GV3 P and GV3 L |
| GV3 D11 $(50 \mathrm{~Hz})$ | GV3 ME | GVA S115 or GVA S125 | GV2, GV3 P and GV3 L |
| GV3 D11 $(60 \mathrm{~Hz})$ | GV3 ME | GVA S115 | GV2, GV3 P and GV3 L |
| GV3 D22 $(50 \mathrm{~Hz})$ | GV3 ME | GVA S225 | GV2, GV3 P and GV3 L |
| GV3 D38 $(50 / 60 \mathrm{~Hz})$ | GV3 ME | GVA S385 or GVA S415 | GV2, GV3 P and GV3 L |

## Padlocking devices and external operator (1)

| Old reference | For circuit-breaker | New reference | For circuit-breaker |
| :--- | :--- | :--- | :--- |
| GV1 V02 | GV3 ME | GV2 V03 | GV2, GV3 P and GV3 L |
| GK3 AV01 | GK3 EF | GV2 V03 | GV2, GV3 P and GV3 L |
| GK3 AP03 | GK3 EF | GV3 AP02 | GV3 P and GV3 L |

[^9]
## TeSys contactors

TeSys d contactors

| 3-pole contactors, 40 to 65 A |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power (kW) at 400 V / AC3 | Old reference | Power connection | Control connection | Type of coil | New reference | Power connection | Control connection | Type of coil |
| 18.5 | LC1D40•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1D40A•• | EverLink | Screw clamp terminals | ~/-- |
| 18.5 | LC1D4011•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1D40A•• | EverLink | Screw clamp terminals | ~/-- |
| 18.5 | LC1D405•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1D40A5••TQ (1) | EverLink | Screw clamp terminals | ~/-- |
| 18.5 | LC1D406•• | Lug type terminals | Lug type terminals | ~/-- | LC1D40A6•• | Lug type terminals | Lug type terminals | ~/-- |
| 18.5 | LC1D40116•• | Lug type terminals | Lug type terminals | ~/-- | LC1D40A6•• | Lug type terminals | Lug type terminals | ~/-- |
| 22 | LC1D50•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1D50A•• | EverLink | Screw clamp terminals | ~/-- |
| 30 | LC1D65•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1D65A•• | EverLink | Screw clamp terminals | ~/-- |
| 4-pole contactors, 60 to 80 A |  |  |  |  |  |  |  |  |
| Maximum current in AC1 | Old reference | Power connection | Control connection | Type of coil | New reference | Power connection | Control connection | Type of coil |
| 60 | LC1D40004•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1DT60A•• | EverLink | Screw clamp terminals | ~/-- |
| 60 | LC1D400046•• | Lug type terminals | Lug type terminals | ~/-- | LC1DT60A6•• | Lug type terminals | Lug type terminals | ~/-- |
| 60 | LP1D40008•• | Screw clamp terminals | Screw clamp terminals | ~/-- | - | - | - | - |
| 60 | LP1D400086•• | Lug type terminals | Lug type terminals | ~/-- | - | - | - | - |
| 80 | LC1D65004•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC1DT80A•• | EverLink | Screw clamp terminals | ~/-- |
| 80 | LC1D650046•• | Lug type terminals | Lug type terminals | ~/-- | LC1DT80A6•• | Lug type terminals | Lug type terminals | ~/-- |
| 80 | LP1D65008•• | Screw clamp terminals | Screw clamp terminals | ~/-- | - | - | - | - |
| 80 | LP1D650086•• | Lug type terminals | Lug type terminals | ~/-- | - | - | - | - |


| Coil voltage: example with a 40 A contactor |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power (kW) at 400 V / AC3 | Old reference | Connector plate width | Frequency <br> Hz | Type of coil | New reference | Connector plate width | Frequency <br> Hz | Type of coil |
| 18.5 | LC1D40•5 | - | 50 | $\sim$ | LC1D40A•7 | - | 50/60 | $\sim$ |
| 18.5 | LC1D40•6 | - | 60 | $\sim$ | LC1D40A•7 | - | 50/60 | $\sim$ |
| 18.5 | LC1D40•7 | - | 50/60 | $\sim$ | LC1D40A•7 | - | 50/60 | $\sim$ |
| 18.5 | LC1D40•D | Standard | - | -- | LC1D40A•D | Wide | - | -- |
| 18.5 | LC1D40*W | Wide | - | --- | LC1D40A•D | Wide | - | -- |
| 18.5 | LP1D40•D | Standard | - | -- | LC1D40A•D | Wide | - | =- |
| 18.5 | LP1D40*W | Wide | - | -- | LC1D40A•D | Wide | - | -- |

(1) Packed in lots of 10 .

## TeSys contactors <br> TeSys d contactors

| 3-pole reversing contactors, 40 to 65 A |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power (kW) at $400 \mathrm{~V} / \mathrm{AC} 3$ | Old reference | Power connection | Control connection | Type of coil | New reference | Power connection | Control connection | Type of coil |
| 18.5 | LC2D40•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC2D40A•• | EverLink | Screw clamp terminals | ~/-- |
| 18.5 | LC2D4011•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC2D40A•• | EverLink | Screw clamp terminals | ~/-- |
| 18.5 | LC2D405•• | Screw clamp terminals | Screw clamp terminals | ~/-- | LC2D40A•• | EverLink | Screw clamp terminals | ~/-- |
| 22 | LC2D50•๑ | Screw clamp terminals | Screw clamp terminals | ~/-- | LC2D50A•• | EverLink | Screw clamp terminals | ~/-- |
| 30 | LC2D65•๑ | Screw clamp terminals | Screw clamp terminals | ~/-- | LC2D65A•• | EverLink | Screw clamp terminals | ~/-- |
| 4-pole reversing contactors, 60 to 80 A |  |  |  |  |  |  |  |  |
| Maximum current in AC1 | Old reference | Power connection | Control connection | Single dual fre | uency coil | New reference |  |  |
| 60 | LC2D40004・セ | Screw clamp terminals | Screw clamp terminals | $\sim$ |  | For custome $2 \times$ LC1 DT6 | -AD 4CM |  |
| 80 | LC2D65004・セ | Screw clamp terminals | Screw clamp terminals | $\sim$ |  | For custome $2 \times$ LC1 DT8 | by <br> LAD 4CM |  |
| Star-delta contactors, 40 to 50 A |  |  |  |  |  |  |  |  |
| Power (kW) at $400 \mathrm{~V} / \mathrm{AC} 3$ | Old reference | Power connection | Control connection | Single and dual frequency coil |  | New reference |  |  |
| 37 | LC3D40•• | Screw clamp terminals | Screw clamp terminals | $\sim$ |  | For customer assembly: <br> $3 \times$ LC1 D40A $\bullet+$ LAD 9SD3 (star-delta kit) |  |  |
| 55 | LC3D50•• | Screw clamp terminals | Screw clamp terminals | $\sim$ |  | For customer assembly: <br> $3 \times$ LC1 D50A $\bullet+$ LAD 9SD3 (star-delta kit) |  |  |

TeSys contactors
TeSys d contactors

| Coils for $\sim$ contactors, 40 to 65 A |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | Old reference | Type of current | Frequency | New reference | Type of current | Frequency |
| V |  |  | Hz |  |  | Hz |
| 12 | LX1D6J5 | $\sim$ | 50 | LXD3J5 | $\sim$ | 50 |
| 20 | LX1D6Z5 or Z 6 or $\mathrm{Z7}$ | $\sim$ | 50 or 60 or 50/60 | - | $\sim$ | 50/60 |
| 24 | LX1D6B5 or B6 or B7 | $\sim$ | 50 or 60 or 50/60 | LXD3B7 | $\sim$ | 50/60 |
| 32 | LX1D6C5 | $\sim$ | 50 | LXD3C7 | $\sim$ | 50/60 |
| 42 | LX1D6 or D5 or D7 | $\sim$ | 50 or 50/60 | LXD3D7 | $\sim$ | 50/60 |
| 48 | LX1D6E5 or E6 or E7 | $\sim$ | 50 or 60 or 50/60 | LXD3E7 | $\sim$ | 50/60 |
| 100 | LX1D6K7 | $\sim$ | 50/60 | LXD3K7 | $\sim$ | 50/60 |
| 110 | LX1D6F5 or F6 or F7 | $\sim$ | 50 or 60 or 50/60 | LXD3F7 | $\sim$ | 50/60 |
| 115 | LX1D6FE7 | $\sim$ | 50/60 | LXD3FE7 | $\sim$ | 50/60 |
| 120 | LX1D6G5 or G8 or G7 | $\sim$ | 50 or 60 or 50/60 | LXD3G7 | $\sim$ | 50/60 |
| 155 | LX1D6GG5 | $\sim$ | 50 | - | $\sim$ | 50/60 |
| 200 | LX1D6 L7 | $\sim$ | 50/60 | LXD3L7 | $\sim$ | 50/60 |
| 208 | LX1D6L6 or LE7 | $\sim$ | 60 or 50/60 | LXD3LE7 | $\sim$ | 50/60 |
| 220 | LX1D6M5 or M6 or M7 | $\sim$ | 50 or 60 or 50/60 | LXD3M7 | $\sim$ | 50/60 |
| 230 | LX1D6P5 or P7 | $\sim$ | 50 or 50/60 | LXD3P7 | $\sim$ | 50/60 |
| 240 | LX1D6U5 or U6 or U7 | $\sim$ | 50 or 60 or 50/60 | LXD3U7 | $\sim$ | 50/60 |
| 256 | LX1D6W5 | $\sim$ | 50 | - | $\sim$ | 50/60 |
| 277 | LX1D6W6 | $\sim$ | 60 | LXD3W7 | $\sim$ | 50/60 |
| 380 | LX1D6Q5 or Q6 or Q7 | $\sim$ | 50 or 60 or 50/60 | LXD3Q7 | $\sim$ | 50/60 |
| 400 | LX1D6V5 or V7 | $\sim$ | 50 or 50/60 | LXD3V7 | $\sim$ | 50/60 |
| 415 | LX1D6N5 or N6 or N7 | $\sim$ | 50 or 60 or 50/60 | LXD3N7 | $\sim$ | 50/60 |
| 440 | LX1D6R5 or R6 or R7 | $\sim$ | 50 or 60 or 50/60 | LXD3R7 | $\sim$ | 50/60 |
| 480 | LX1D6T6 | $\sim$ | 60 | LXD3T7 | $\sim$ | 50/60 |
| 500 | LX1D6S5 | $\sim$ | 50 | LXD3S7 | $\sim$ | 50/60 |
| 550 | LX1D6SF5 | $\sim$ | 50 | - | $\sim$ | 50/60 |
| 575 | LX1D6S7 | $\sim$ | 50/60 | LXD3SC7 | $\sim$ | 50/60 |
| 600 | LX1D6X6 | $\sim$ | 60 | LXD3X7 | $\sim$ | 50/60 |
| 660 | LX1D6Y5 | $\sim$ | 50 | LXD3YC7 | $\sim$ | 50/60 |


| Thermal overload relays up to 65 A |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Old reference | Setting range Ir | Class | Type | Power connection | New reference | Setting range Ir | Class | Type | Power connection |
|  | A |  |  |  |  | A |  |  |  |
| LRD3306 | 1...1.6 | 10 | Differential | Screw clamp terminals | LRD06 | 1...1.6 | 10A | Differential | Screw clamp terminals |
| LRD3307 | 1.6...2.5 | 10 | Differential | Screw clamp terminals | LRD07 | 1.6...2.5 | 10A | Differential | Screw clamp terminals |
| LRD3308 | 2.5... 4 | 10 | Differential | Screw clamp terminals | LRD08 | 2.5... 4 | 10A | Differential | Screw clamp terminals |
| LRD3310 | 4... 6 | 10 | Differential | Screw clamp terminals | LRD10 | 4... 6 | 10A | Differential | Screw clamp terminals |
| LRD3312 | 5.5... 8 | 10 | Differential | Screw clamp terminals | LRD12 | 5.5... 8 | 10A | Differential | Screw clamp terminals |
| LRD3314 | 7... 10 | 10 | Differential | Screw clamp terminals | LRD14 | 7... 10 | 10A | Differential | Screw clamp terminals |
| LRD3316 | 9... 13 | 10 | Differential | Screw clamp terminals | LRD313 | 9... 13 | 10A | Differential | EverLink |
| LRD3321 | 12... 18 | 10 | Differential | Screw clamp terminals | LRD318 | 12... 18 | 10A | Differential | EverLink |
| LRD3322 | 17... 25 | 10 | Differential | Screw clamp terminals | LRD325 | 17... 25 | 10A | Differential | EverLink |
| LRD3353 | 23... 32 | 10 | Differential | Screw clamp terminals | LRD332 | 23... 32 | 10A | Differential | EverLink |
| LRD3355 | 30... 40 | 10 | Differential | Screw clamp terminals | LRD340 | 30... 40 | 10A | Differential | EverLink |
| LRD3357 | 37... 50 | 10 | Differential | Screw clamp terminals | LRD350 | 37... 50 | 10A | Differential | EverLink |
| LRD3359 | 48... 65 | 10 | Differential | Screw clamp terminals | LRD365 | 48... 65 | 10A | Differential | EverLink |
| LR2D33•• | 1... 65 | 10 | Differential | Screw clamp terminals | LRD3•• | 9... 65 | 10A | Differential | EverLink |
| LRD33•^A66 | 1... 65 | 10 | Differential | Lug type terminals | LRD3••6 | 9... 65 | 10A | Differential | Lug type terminals |
| LR2D33••A66 | 1... 65 | 10 | Differential | Lug type terminals | LRD3••6 | 9... 65 | 10A | Differential | Lug type terminals |
| LR2D35•• | 17... 65 | 20 | Differential | Screw clamp terminals | LRD3**L | 9... 65 | 20 | Differential | EverLink |
| LR3D33•• | 17... 65 | 10 | Non differential | Screw clamp terminals | LR3D3•• | 9... 65 | 10A | Non differential | EverLink |
| LR3D35•๑ | 17... 65 | 20 | Non differential | Screw clamp terminals | - | - | - | - | - |


| Suppressor modules for contactors, 40 to 65 A |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Setting range v | Old reference | Type of current | Type | New reference | Type of current | Type |
| 24... 48 | LA4DA1E | $\sim$ | RC circuit | LAD4RC3E | $\sim$ | RC circuit |
| $110 \ldots 240$ | LA4DA1U | $\sim$ | RC circuit | LAD4RC3U | $\sim$ | RC circuit |
| $24 \ldots 48$ | LA4DA2E | $\sim$ | RC circuit | LAD4RC3E | $\sim$ | RC circuit |
| $50 . .127$ | LA4DA2G | $\sim$ | RC circuit | LAD4RC3G | $\sim$ | RC circuit |
| $380 \ldots 415$ | LA4DA2N | $\sim$ | RC circuit | LAD4RC3N | $\sim$ | RC circuit |
| >24 | LA4DB2B | $\sim$ | Bidirectional peak limiting diode | LAD4T3B | $\sim /-$ | Bidirectional peak limiting diode |
| $25 \ldots 72$ | LA4DB2S | $\sim$ | Bidirectional peak limiting diode | LAD4T3G | ~/-- | Bidirectional peak limiting diode |
| >24 | LA4DB3B | -- | Bidirectional peak limiting diode | LAD4T3B | $\sim /-$ | Bidirectional peak limiting diode |
| $25 \ldots 72$ | LA4DB3S | -- | Bidirectional peak limiting diode | LAD4T3G | $\sim / \ldots$ | Bidirectional peak limiting diode |
| $24 \ldots 250$ | LA4DC3U | - | Flywheel diode | LAD4D3U | -- | Flywheel diode |
| $24 \ldots 48$ | LA4DE2E | $\sim$ | Varistor | LAD4V3E | $\sim /-$ | Varistor |
| $50 \ldots 127$ | LA4DE2G | $\sim$ | Varistor | LAD4V3G | $\sim /-$ | Varistor |
| $110 \ldots 250$ | LA4DE2U | $\sim$ | Varistor | LAD4V3U | ~/- | Varistor |
| $24 \ldots 48$ | LA4DE3E | -- | Varistor | LAD4V3E | $\sim /-$ | Varistor |
| $50 \ldots 127$ | LA4DE3G | =- | Varistor | LAD4V3G | $\sim /=$ | Varistor |
| $110 \ldots 250$ | LA4DE3U | -- | Varistor | LAD4V3U | $\sim /$ - | Varistor |


| Accessories for contactors and relays, 40 to 65 A |  |  |  |
| :---: | :---: | :---: | :---: |
| Old reference | Description | New reference | Notes |
| LA4DT0U | Electronic serial timer module, 0.1 to 2 s . <br> 24...250V | LA4DT0U | Use accessory LAD4BB3 |
| LA4DT2U | Electronic serial timer module, 1.5 to 30 s. $24 \ldots 250 \mathrm{~V}$ | LA4DT2U | Use accessory LAD4BB3 |
| LA4DT4U | Electronic serial timer module, 25 to 500 s . <br> 24...250V | LA4DT4U | Use accessory LAD4BB3 |
| LA6DK10B | Mechanical latch block 24 V ~ | LAD6K10B |  |
| LA6DK10E | Mechanical latch block 42/48 V ~ | LAD6K10E |  |
| LA6DK10F | Mechanical latch block 110/127 V ~ | LAD6K10F |  |
| LA6DK10M | Mechanical latch block 220/240 V ~ | LAD6K10M |  |
| LA6DK10Q | Mechanical latch block 380/415 V ~ | LAD6K10Q |  |
| LA7D03B | Remote electrical reset 24 V | LAD703B |  |
| LA7D03DD | Remote electrical reset 96 V | LAD703DD |  |
| LA7D03E | Remote electrical reset 48 V | LAD703E |  |
| LA7D03F | Remote electrical reset 110 V | LAD703F |  |
| LA7D03J | Remote electrical reset 12 V | LAD703J |  |
| LA7D03M | Remote electrical reset 220/230 V | LAD703M |  |
| LA7D03N | Remote electrical reset $415 / 440 \mathrm{~V}$ | LAD703N |  |
| LA7D03Q | Remote electrical reset 380/400 V | LAD703Q |  |


| Accessories for contactors and relays, 40 to 65 A (continued) |  |  |  |
| :---: | :---: | :---: | :---: |
| Old reference | Description | New reference | Notes |
| LA7D03Q | Remote electrical reset 380/400 V | LAD703Q |  |
| LA7D1020 | Adapter for door mounted operator | - | No equivalent - Not necessary with the new range. |
| LA7D305 | Remote control by flexible cable | LAD7305 |  |
| LA7D3058 | Terminal block adapter for mounting a relay beneath a contactor | - | No equivalent |
| LA7D3064 | Terminal block for clip-on mounting of a relay on 35 mm rail | LAD96560 | EverLink terminal block |
| LA7D901 | Stop button locking device | - | No equivalent |
| LA7D902 | Mounting plate | - | No equivalent - Not necessary with the new range. |
| LA7D903 | Marker holder for contactor | LAD90 |  |
| LA9D09966 | Retrofit coil for 3-pole contactor | LAD4BB3 |  |
| LA9D4002 | Mechanical interlock for reversing contactors | LAD4CM |  |
| LA9D40961 | Link for parallel connection for 2 poles | LAD9P32 |  |
| LA9D40963 | Link for parallel connection for 4 poles | $2 \times$ LAD9P33 |  |
| LA9D50978 | Kits for assembly of reversing contactors, 40 to 65A | LAD9R3 |  |
| LA9D6567 | Control circuit take-off from main pole | - | No equivalent |
| LA9D6569 | Set of power connections for contactor | LA9D65A69 |  |
| LA9D92 | Marker holder for contactor | LA9D90 |  |
| LAD9ET2 | Safety cover | LAD9ET1 |  |
| XB5 AA86102 | Operating head for spring return pushbutton. Reset | XB5 AA86102 | Same product |
| XB5 AL84101 | Operating head for spring return pushbutton. Stop | XB5 AL84101 | Same product |

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[^0]:    (1) For LRD 313 to 365 relays: BTR hexagon socket head screws EverLink® system in accordance with local electrical wiring regulations, a size 4 insulated Allen key must be used (reference LAD ALLEN4, see page 173).

[^1]:    (1) Standard IEC 60947-4-1 specifies a tripping time for 7.2 times the setting current $I_{R}$ : class 10 A : between 2 and 10 seconds
    (2) BTR screws: hexagon socket head. In accordance with local electrical wiring regulations, a size 4 insulated Allen key must be used (reference LAD ALLEN4, see page 173).

[^2]:    (1) Standard IEC 60947-4-1 specifies a tripping time for 7.2 times the setting current $I_{R}$ : class 20: between 6 and 20 seconds

[^3]:    (1) Can only be mounted on RH side of relay LRD01... 35 and LRD313... 365

[^4]:    (1) Please consult our catalogue "Power supplies, splitter boxes and interfaces".
    (2) Please consult our catalogue "Advantys STB I/O. The open solution".

[^5]:    1 Circuit-breaker and contactor support plate
    2 Power connection module
    3 Power splitter box
    4 Control splitter box
    5 Upstream terminal block
    6 Outgoing terminal block
    (1) 2 starters: $90 \mathrm{~mm}, 4$ starters: $180 \mathrm{~mm}, 8$ starters: 360 mm .

[^6]:    (1) Can be fixed at 43 mm

[^7]:    (1) le $\leqslant 17$ A for electrical durability, le $\leqslant 100$ A for occasional duty.
    (2) le $>17$ A for electrical durability, le $>100$ A for occasional duty.
    (3) The value $6 P$ (in watts) is based on practical observations and is considered to represent the majority of d.c. magnetic loads up to the maximum limit of $P=50$ Wi.e. 6P $=300 \mathrm{~ms}=L / R$.
    Above this, the loads are made up of smaller loads in parallel. The value 300 ms is therefore a maximum limit whatever the value of current drawn.

[^8]:    (1) To avoid increasing the voltage drop due to inrush current, this resistor must be brought into

[^9]:    (1) The old references are still available for circuit-breakers GV3 ME80 and GK3 EF80.

